STPA APPLIED TO A NEURAL NETWORK-CONTROLLED AIRCRAFT

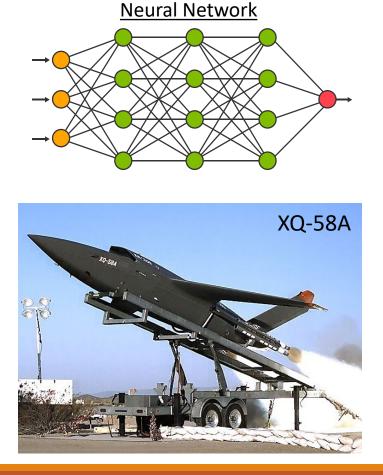
RYAN BOWERS – 40^{TH} FLIGHT TEST SQUADRON

DR. JOHN THOMAS – MASSACHUSETTS INSTITUTE OF TECHNOLOGY

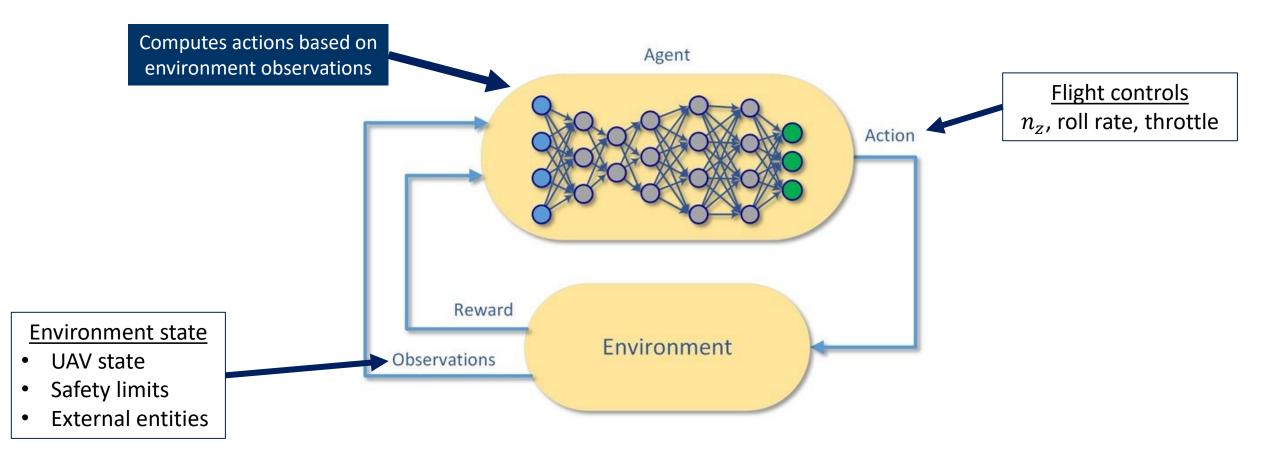
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Overview

- 40th FLTS: flight test for AI-enabled autonomous aircraft
- July 2023: First flight test of a group-5 UAV flown by machine learning agents
- Agents trained using deep reinforcement learning
- Applied STPA before flight test



Deep Reinforcement Learning Agents



System Considerations for Safety

ML agents can be difficult to explain

Agents trained in simulation, then transitioned to real life

 UAV and agents developed under completely separate programs before integrating

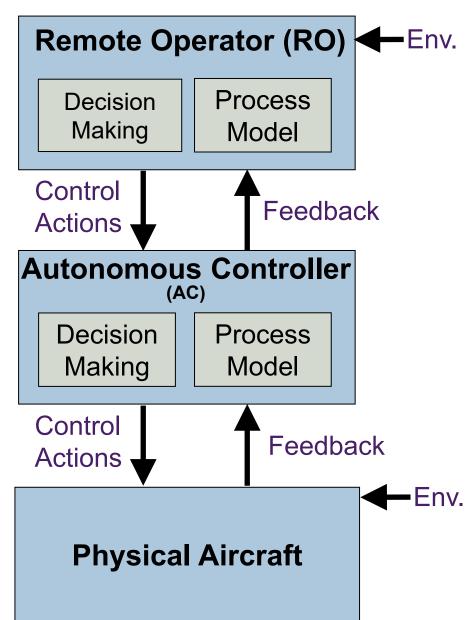
Three-Pronged Flight Test Safety Approach

(1) UAV Mechanisms	(2) Autonomy Mechanisms	(3) Test Procedures
Envelope trips: Disables agent if speed/altitude limits exceeded	Simulation Training: Agents were trained to stay within limits.	Manual Disable: Remote pilot can disable agent at anytime.
Command Limiters: Agent control inputs are clipped to stay within min and max bounds.	Redundant envelope trips: Agent disables itself if limits exceeded.	Abort Limits: Manually disable if any limits exceeded.
		Briefing Items: Team briefed on possible unsafe agent behavior.

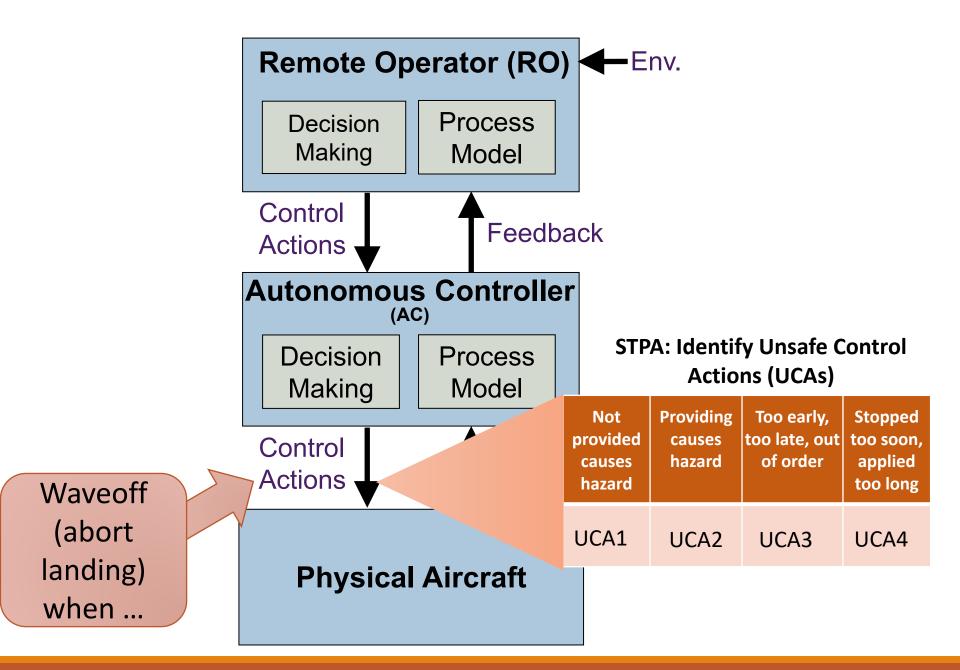
STPA: System Theoretic Process Analysis



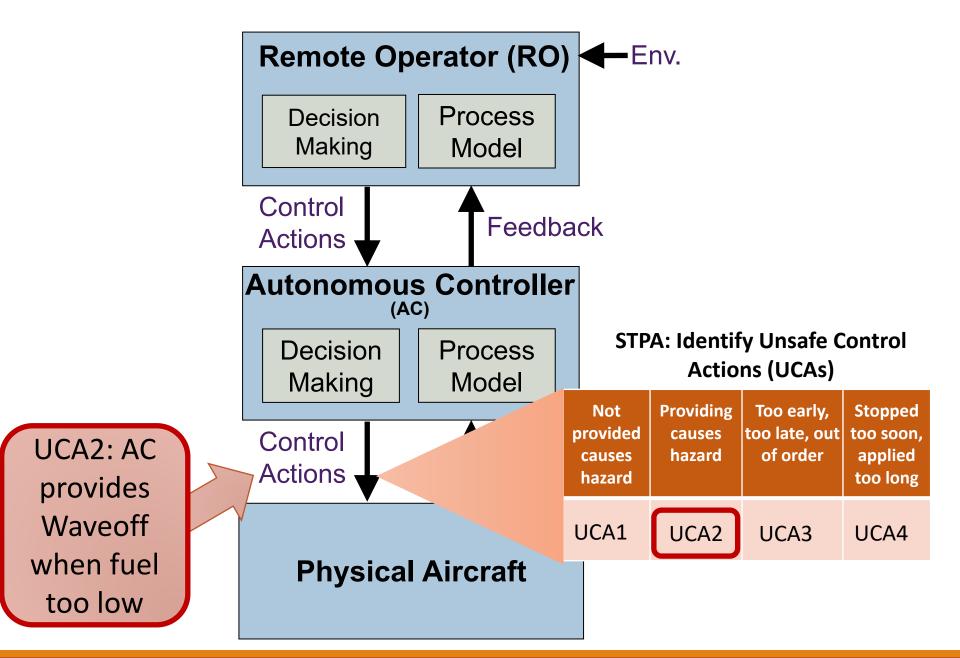




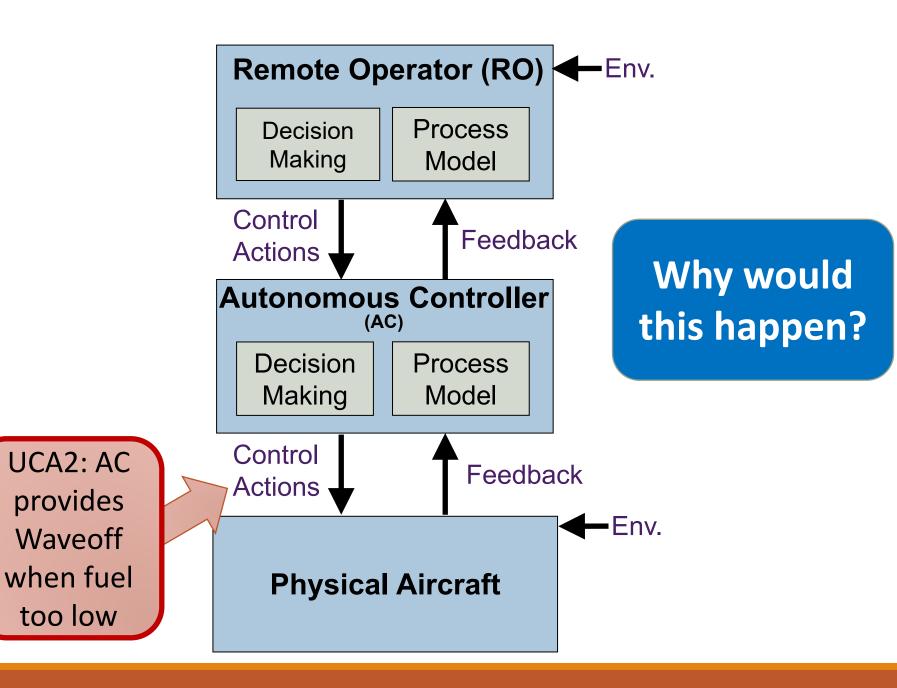






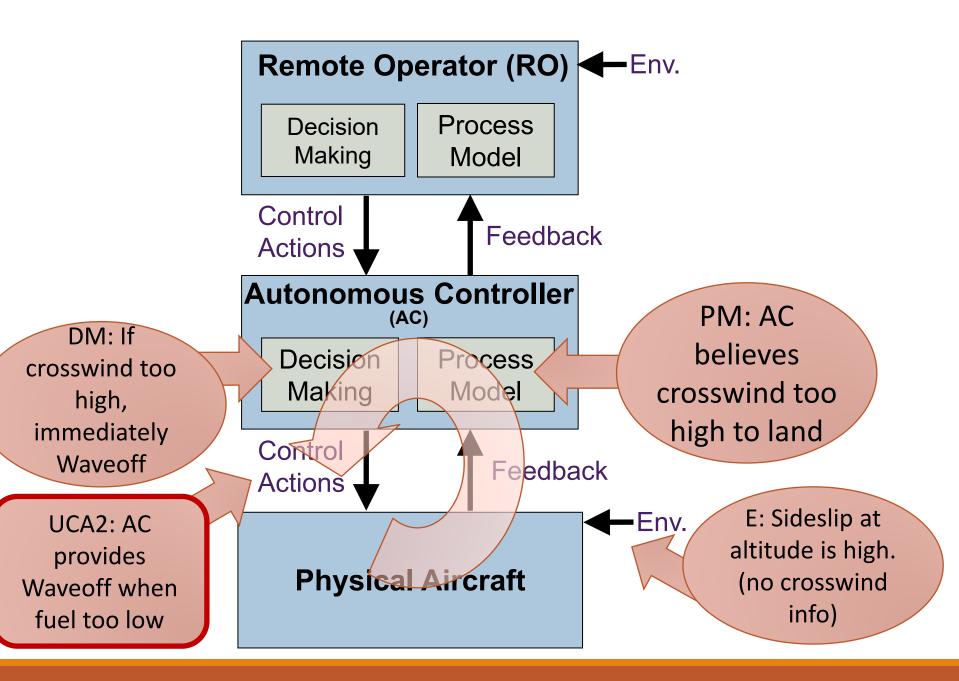






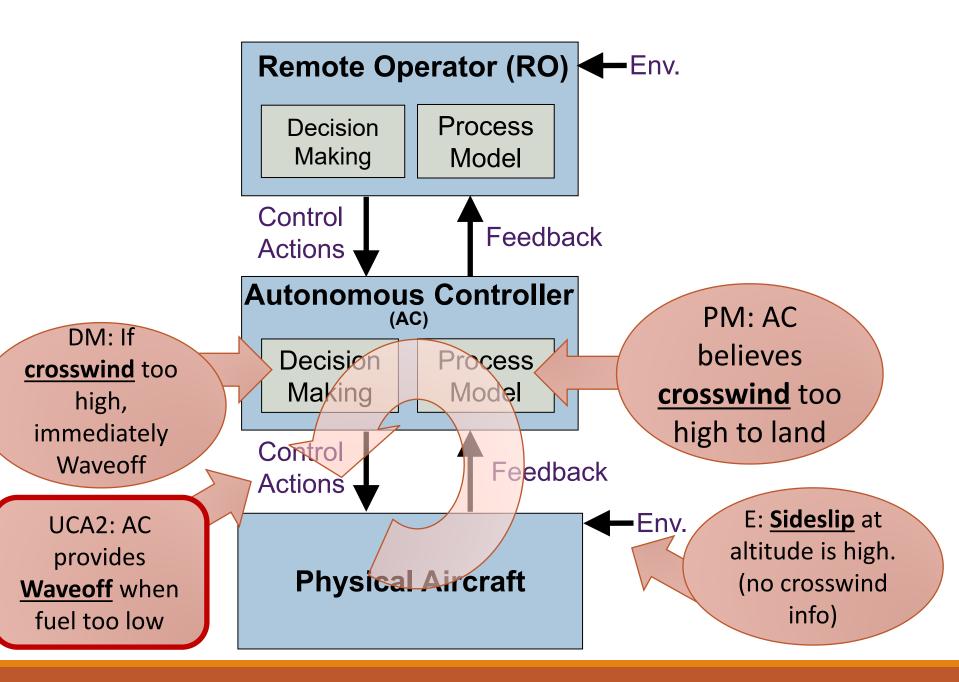


E.g., X-47B UAV integrated into carrier operations alongside manned aircraft. Provides autonomous launch, flight, follow manned A/C, carrier landing, etc.

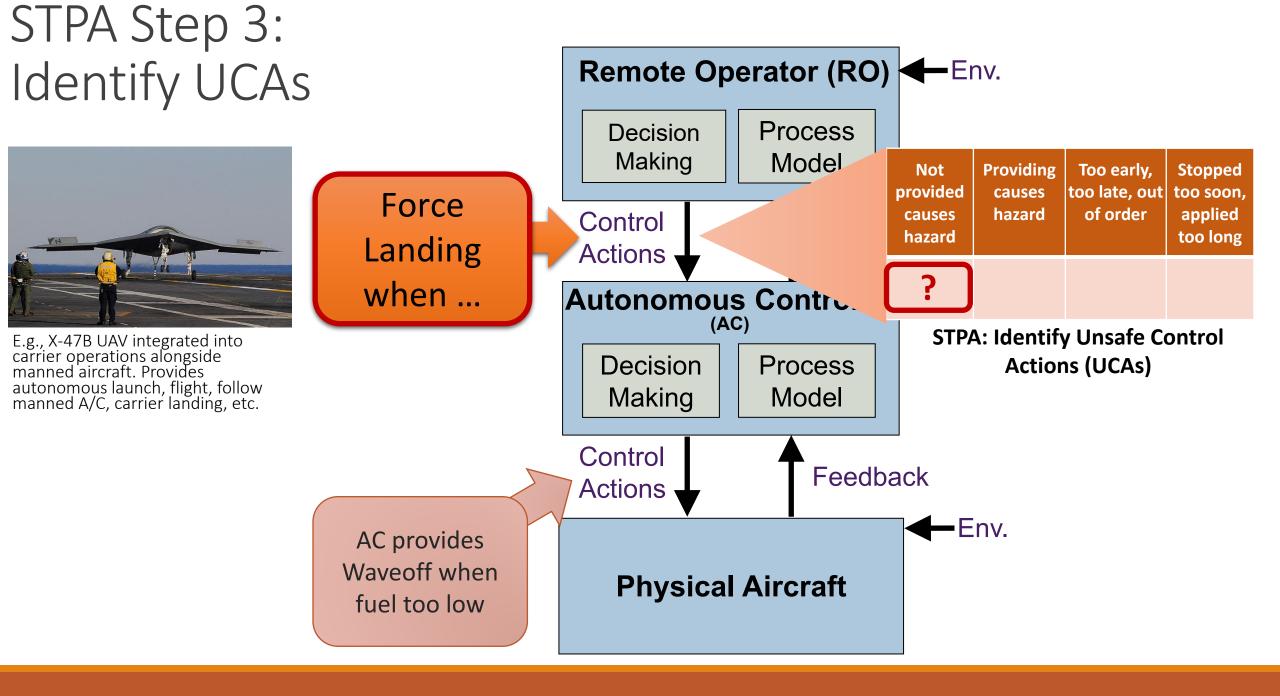




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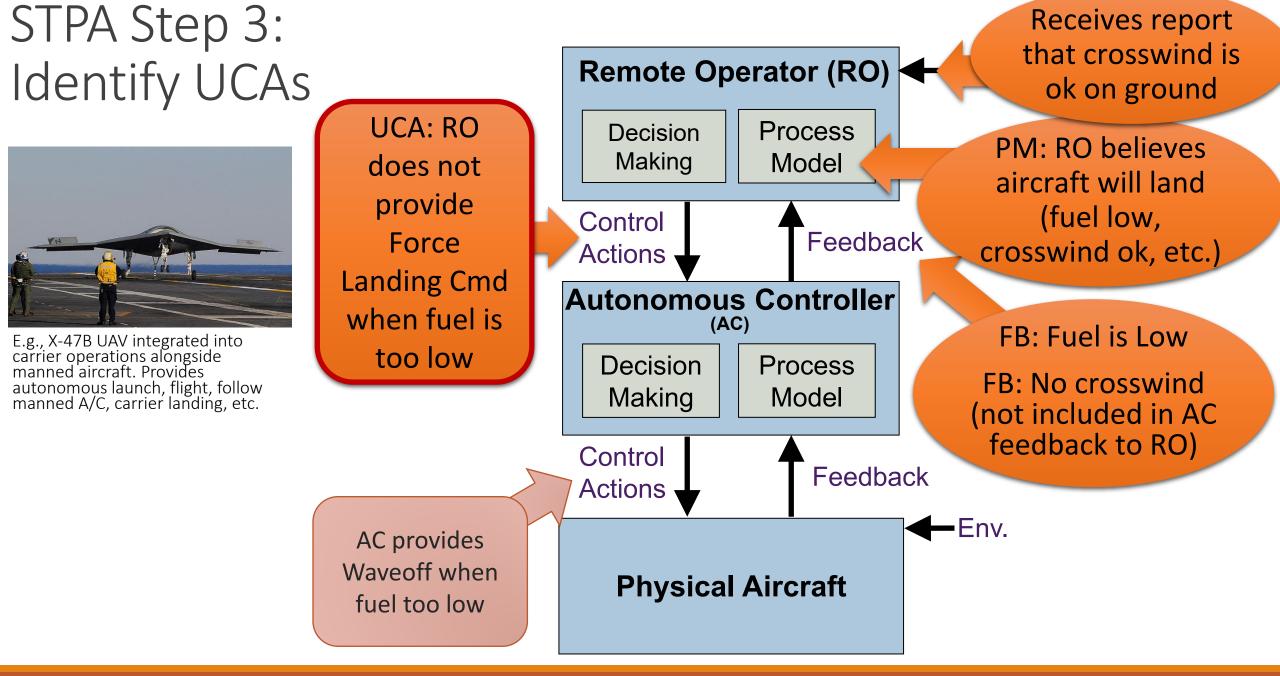


STPA applied to humans (FTEs, Pilots, etc.)

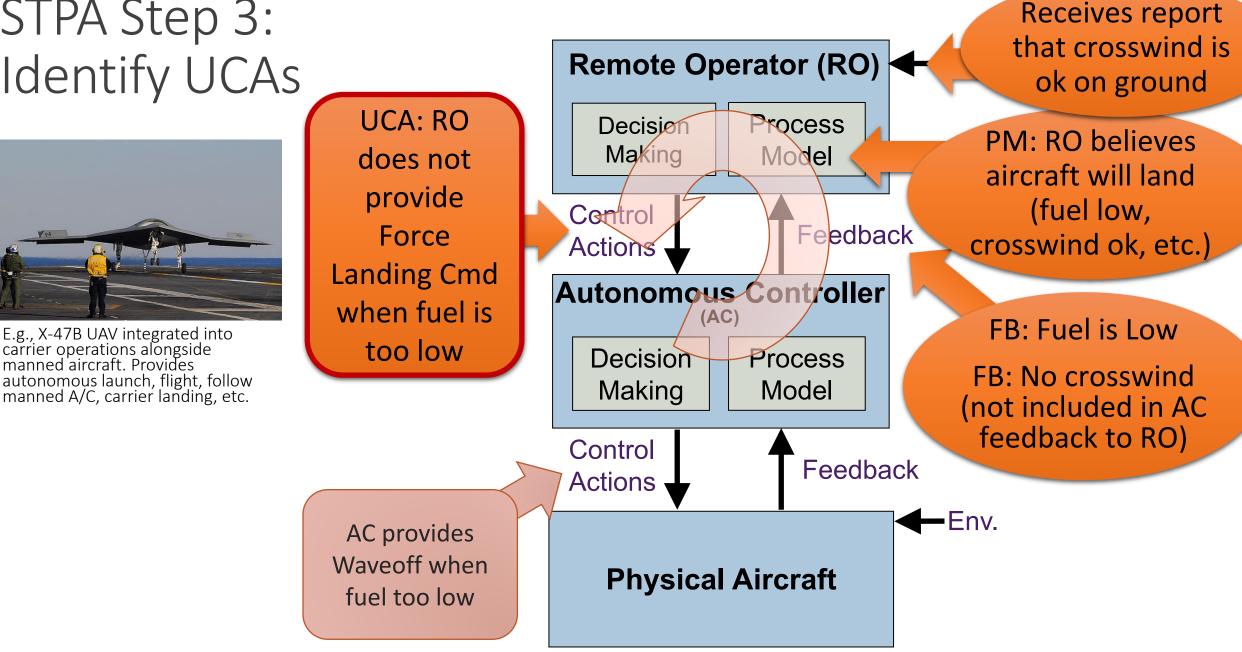


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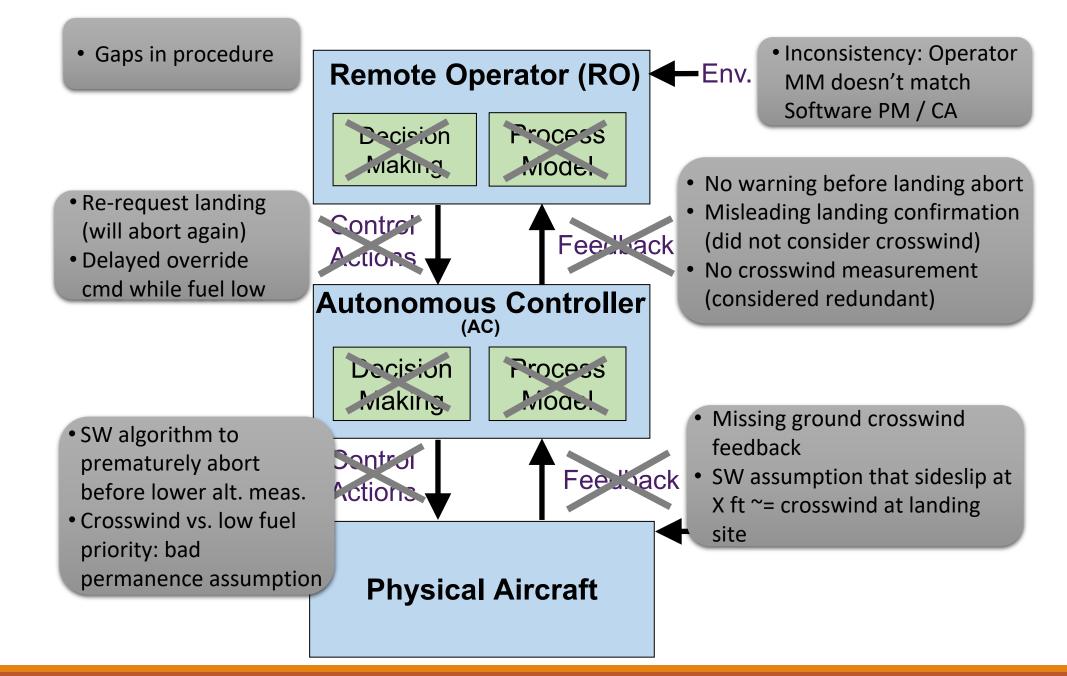




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Results

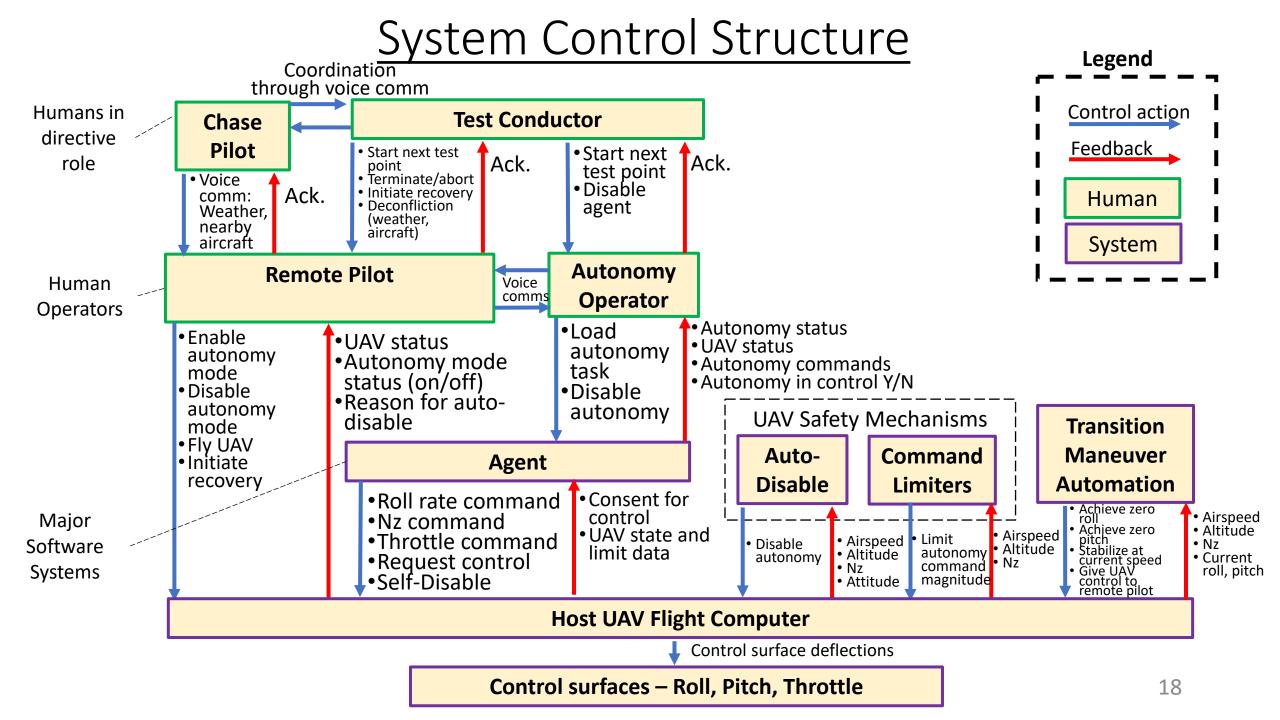


STPA Application

Session 1: 4-day training + application (UAV only) Session 2: 5-day training + application (UAV + AI) Session 3: 2-day application (UAV + more AI detail)

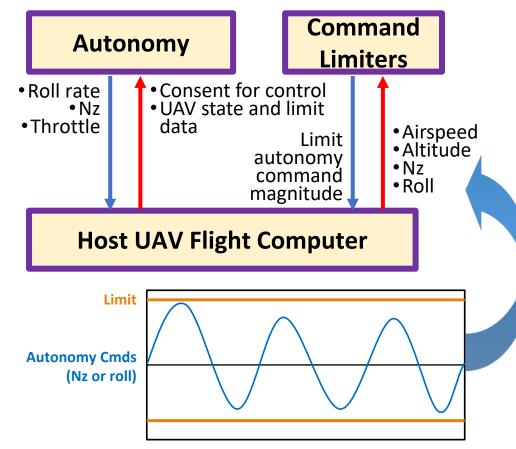
Scope of analysis:

- Focus on flight test ops rather than internal system design
- Black-box AI could do anything at any time
- Can the Autonomy Safety Sandbox handle all situations?



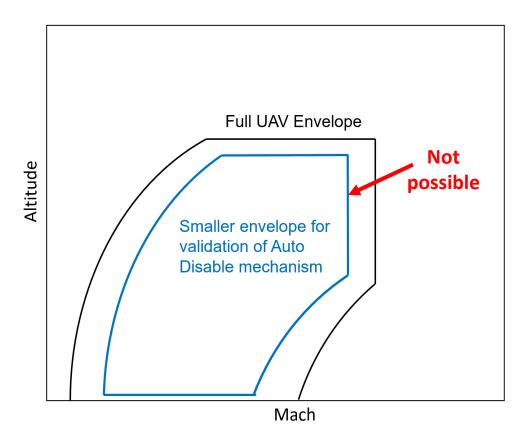
Finding 1: Limitations of Command Limiters

- Command limiters not complex enough to prevent some unsafe/inefficient commands
- No prevention of unsafe input combinations
- No awareness of time history divergent oscillatory control inputs possible
- Recommendation: implement mechanism to prevent unsafe maneuvers



Finding 2: Inflexible UAV Auto-Disable Mechanism

- Auto-Disable altitude/airspeed bounds could not be easily modified
- Could not test Auto-Disable mechanism without assaulting the real limits
- Recommendations:
 - Make limit enforcement mechanisms flexible
 - Early tester involvement in system design

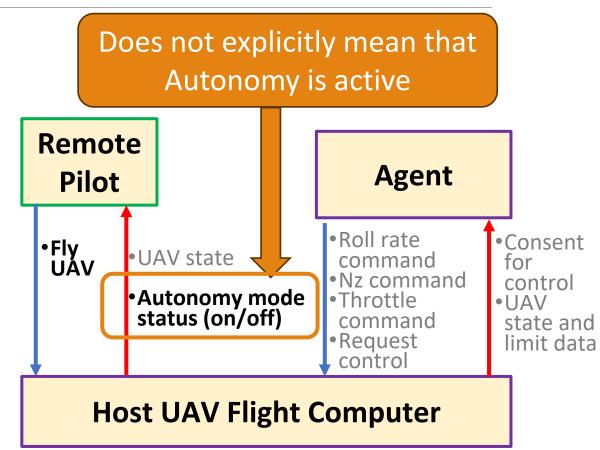


Finding 3: Incomplete Feedback from Autonomy to Remote Pilot

Remote pilot had no direct indication of agent's status or actions

 "Autonomy mode" did not always mean the agent was in control.

 Recommendation: Provide unambiguous indication of agent status to the remote pilot.



Conclusions – Autonomy Safety Sandbox

Three-pronged safety framework was effective but imperfect

- UAV safety mechanisms would not prevent all likely concerns
- Can mitigate those concerns by adding/modifying test procedures, but that tends to be heavy handed

Some issues required band-aids because system design was fixed – recommend STPA during design

Conclusions – Use of STPA

- STPA was effective in identifying new test hazards and gaps
- Does not need to be the only method use it as it makes sense
- Requires resources time, personnel availability
 - Recommend 5+ days for detailed analysis
 - Invite the test team, operators, system SMEs
 - Bring in STPA experts if possible
 - In-person participation highly recommended

Questions?

