

# Lessons-learned from Applying STAMP Safety and Security Analysis on AEB for L4 Autonomous Driving

Shefali Sharma<sup>1</sup>, Adan Flores<sup>1</sup>, Carlos Moreno<sup>1</sup>, Chris Hobbs<sup>2</sup>, Jeff Stafford<sup>3</sup>, Kamal Lamichhane<sup>1</sup>, Waleed Khan<sup>1</sup> and Sebastian Fischmeister<sup>1</sup>

<sup>1</sup> University of Waterloo, Waterloo, ON, Canada

<sup>2</sup>QNX Software Systems Limited, Kanata, ON, Canada

<sup>3</sup>Renesas Electronics America Inc., Farmington Hills, MI, USA

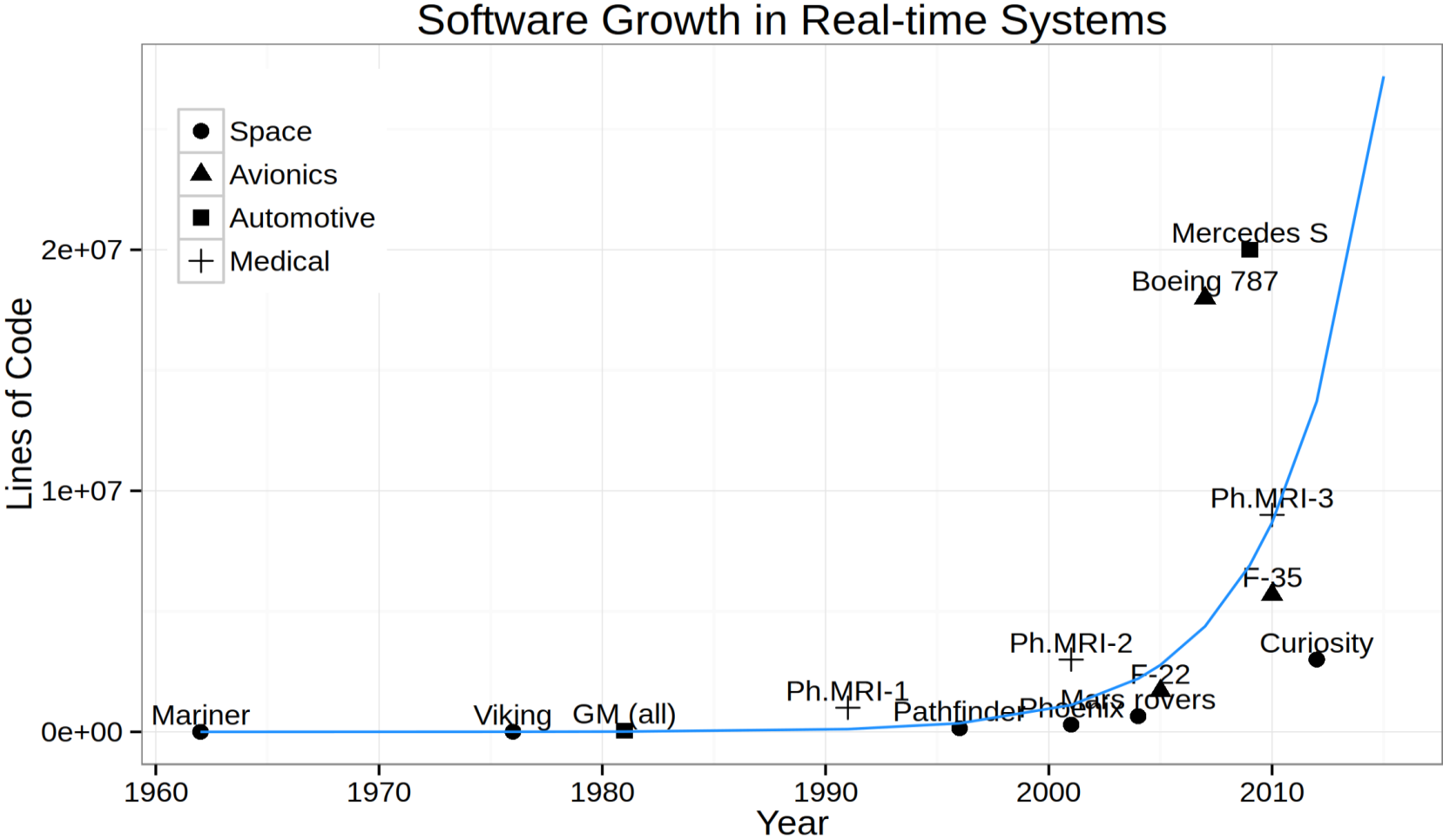
27<sup>th</sup> March, 2018



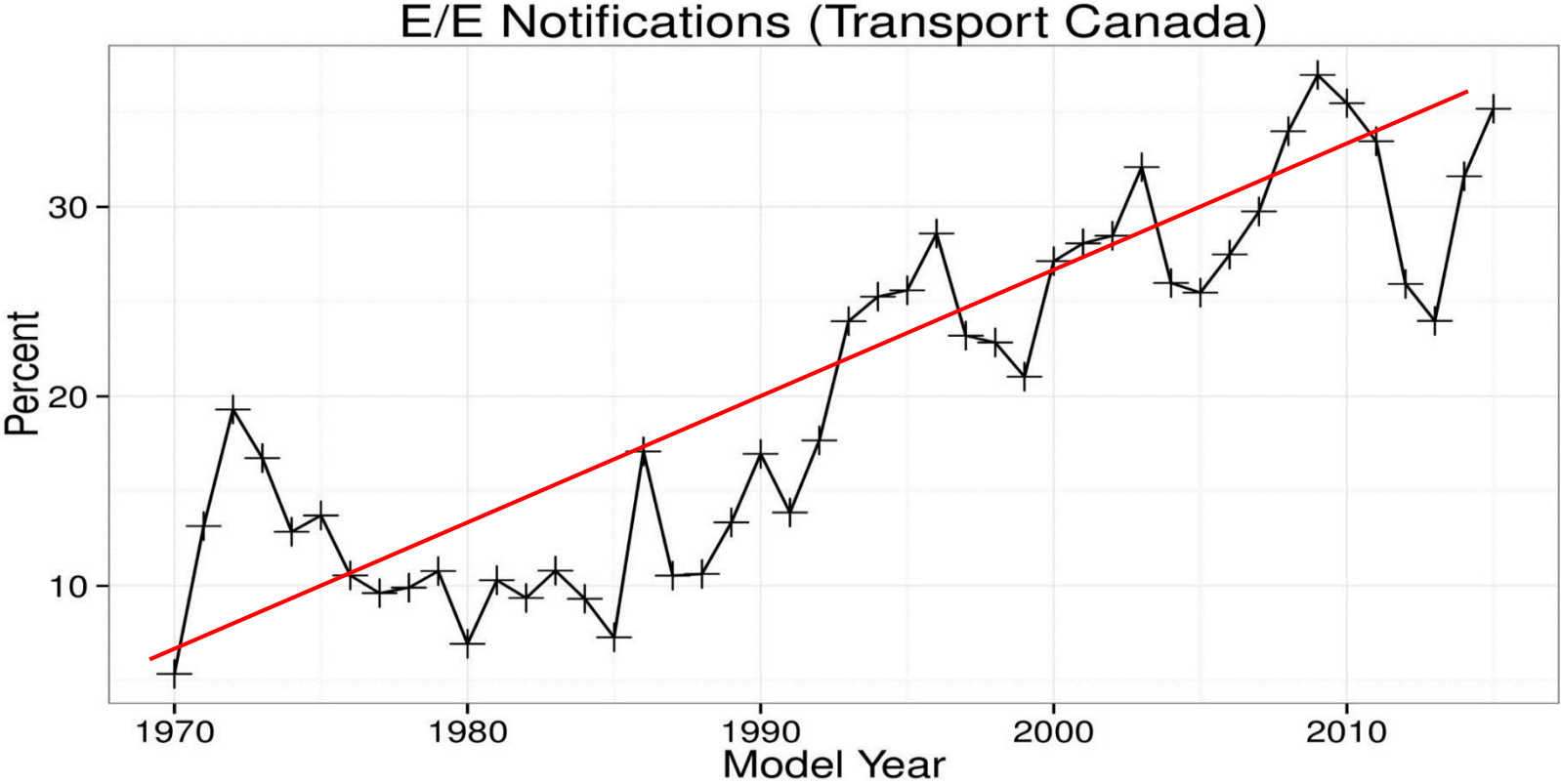
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# Code Complexity is Increasing



# Recalls Are Increasing



Source: Johnson, T. T., R. Gannamaraju, and S. Fischmeister, "A Survey of Electrical and Electronic (E/E) Notifications for Motor Vehicles", 24th International Technical Conference on the Enhanced Safety of Vehicles (ESV), Gothenburg, Sweden, pp. 1--15, 2015.



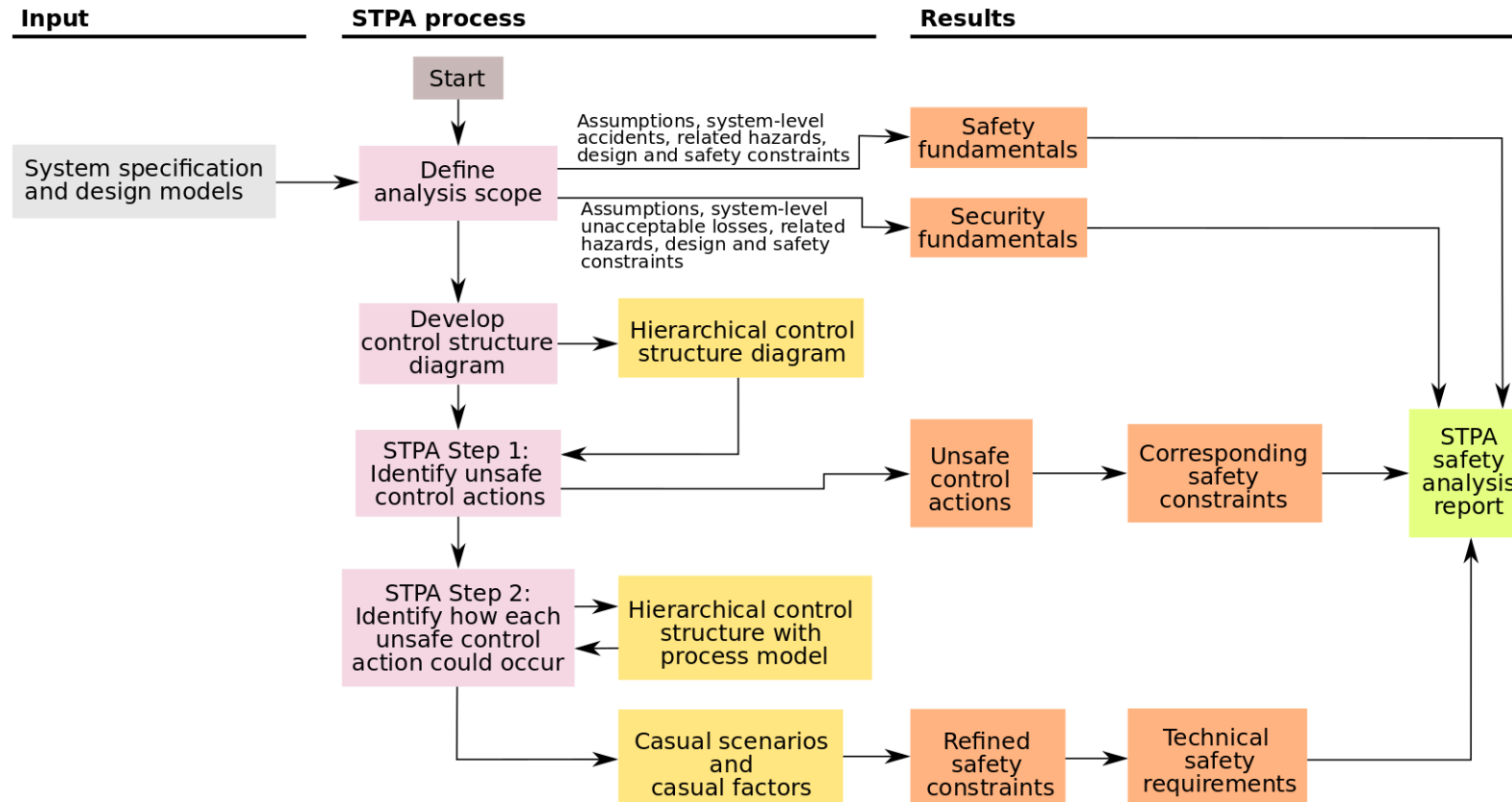
# Scope & Purpose

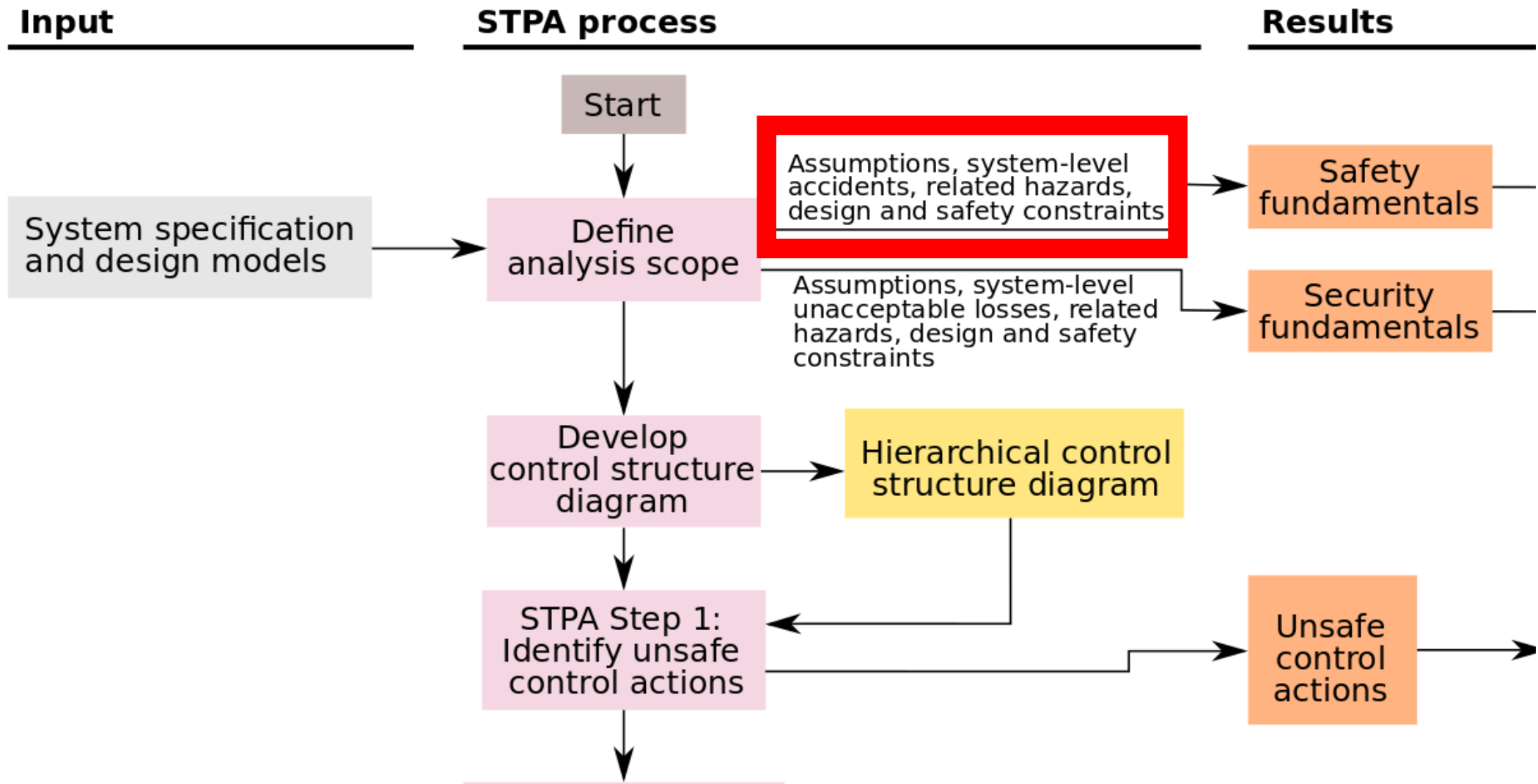
- *Scope* – A safety and security analysis on existing L4 architecture
- *Purpose* – To improve the design of L4 vehicle based on the requirements that resulted in the analysis
- Why Autonomous Emergency Braking (AEB)?
- Security analysis is limited to impact on functional safety



# Methodology

The methodology used combined safety and security analysis.





# Lessons learned

- *Assumptions:*

Limiting conditions that act as a basis for the analysis

- *Accident section:*

Identification of accidents lacks a systematic approach

- *Hazard section:*

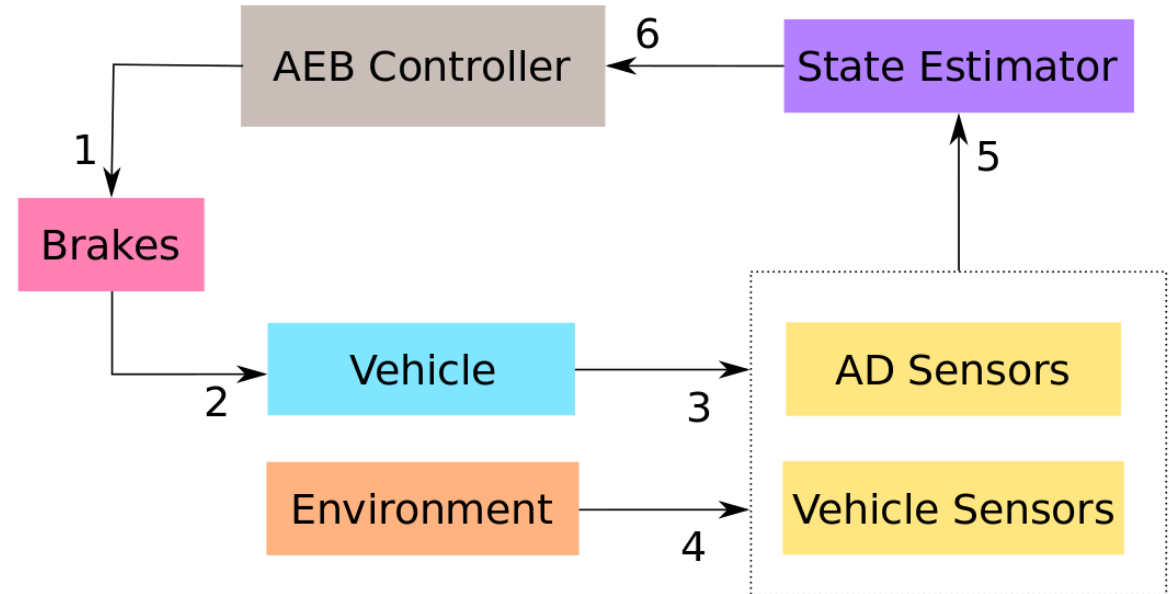
Integrated safety and safety related security hazards in a single report



# Control loop structure

Unsafe Control Actions (UCA) consider two states:

- Braking Force Command (BFC) disengaged
- BFC engaged (modulated engagement ranging from 0%-100%)



## Color Coding:

	Controller		Process Model
	Actuator		Sensors
	Vehicle		External Influence

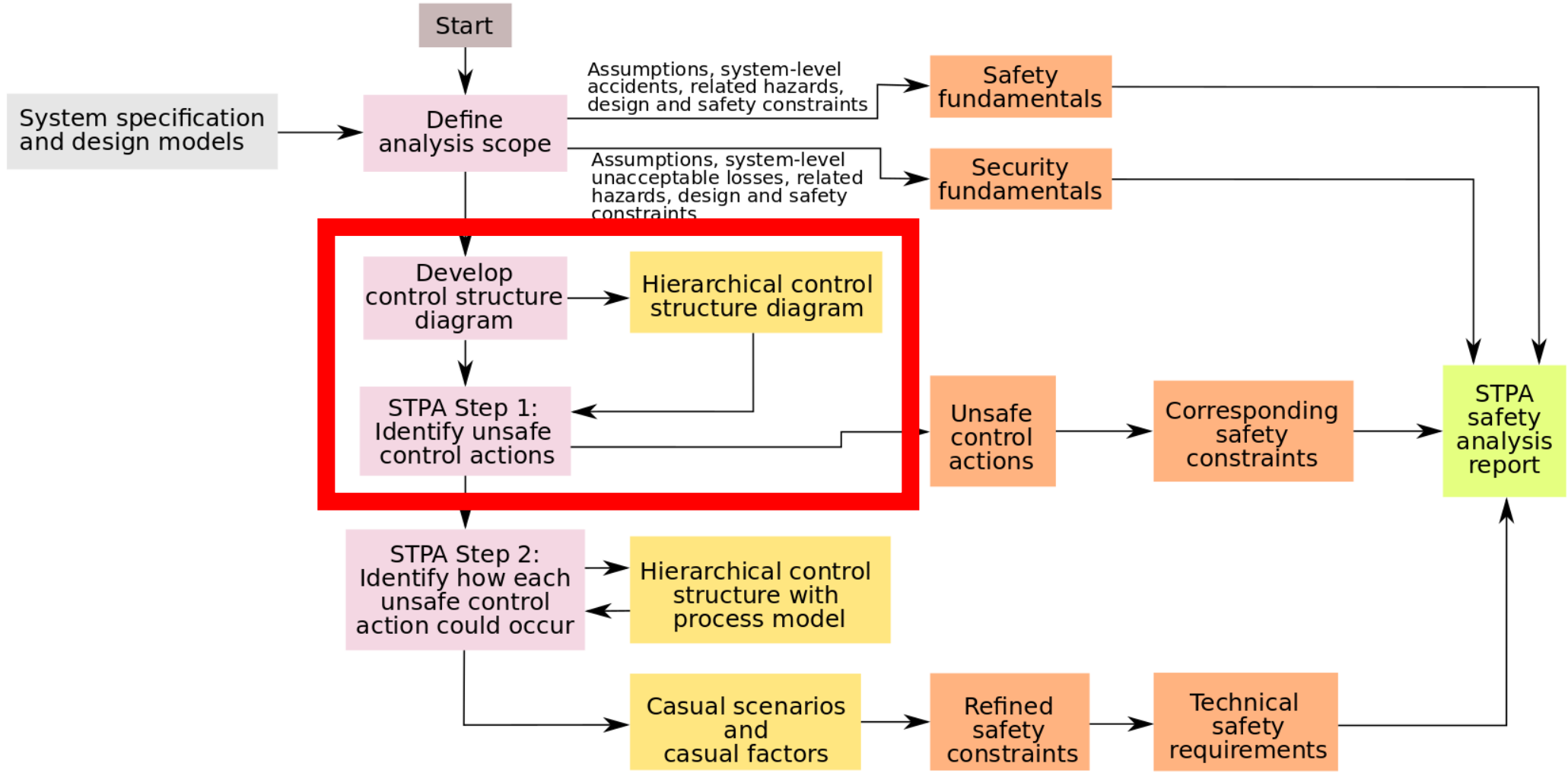




**Input**

**STPA process**

**Results**



# Lessons learned

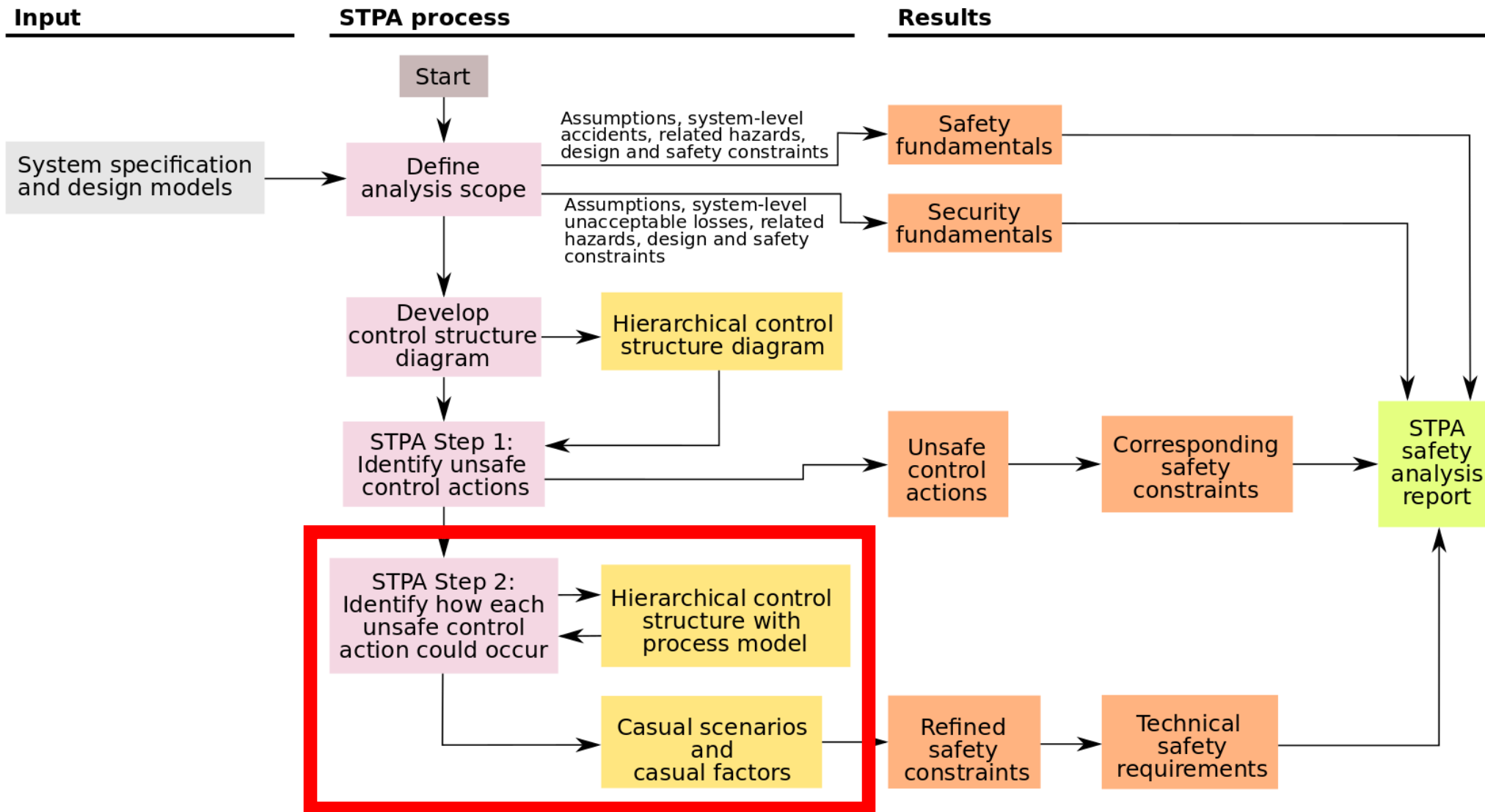
➤ *From control diagram:*

The control diagram must represent the basic blocks with generic functionalities and terms

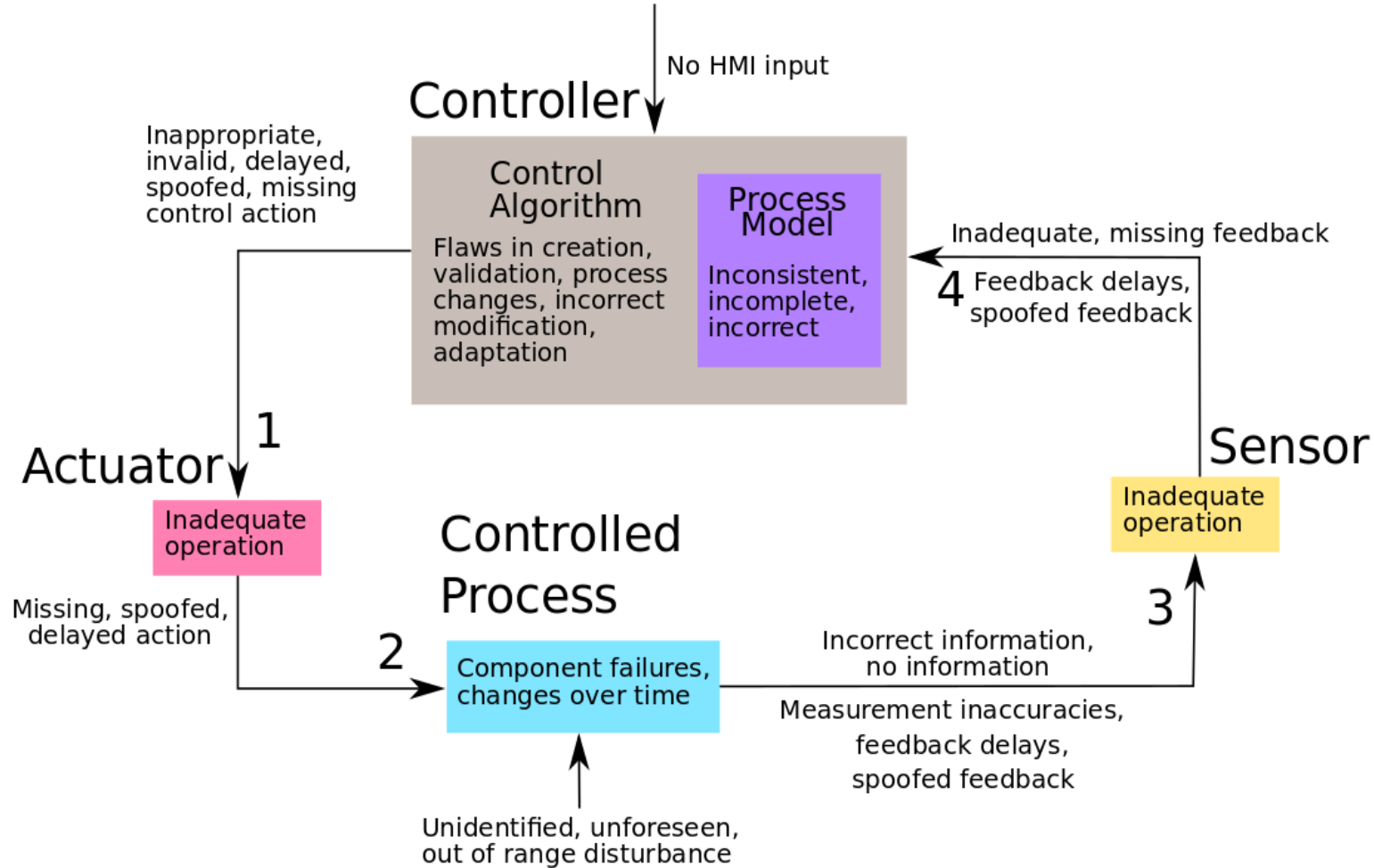
➤ *From UCA:*

Repeated refinement resulted in additional scenarios and causal factors





# Potential control flaws



# Systematic approach for causal factors

➤ Actions regarding data considered per block in the control structure:

- Missing
- Inadequate
- Incorrect
- Delayed

➤ Reasons for unsafe actions:

- Spoofing
- Component failure
- Electrical requirements not met
- Communication failure

Blocks	Actions	Reasons
Sensors(EPS, Localization data, Vehicle speed, Local planner, object identification sensor)		
Controller		
Actuator		
Controlled process		



# Lessons learned

- *Causal scenarios:*

Depending on the type of functionality under consideration, the approach needs to be modified

- *Causal factors:*

Current approach is more systematic and avoids mental exercise



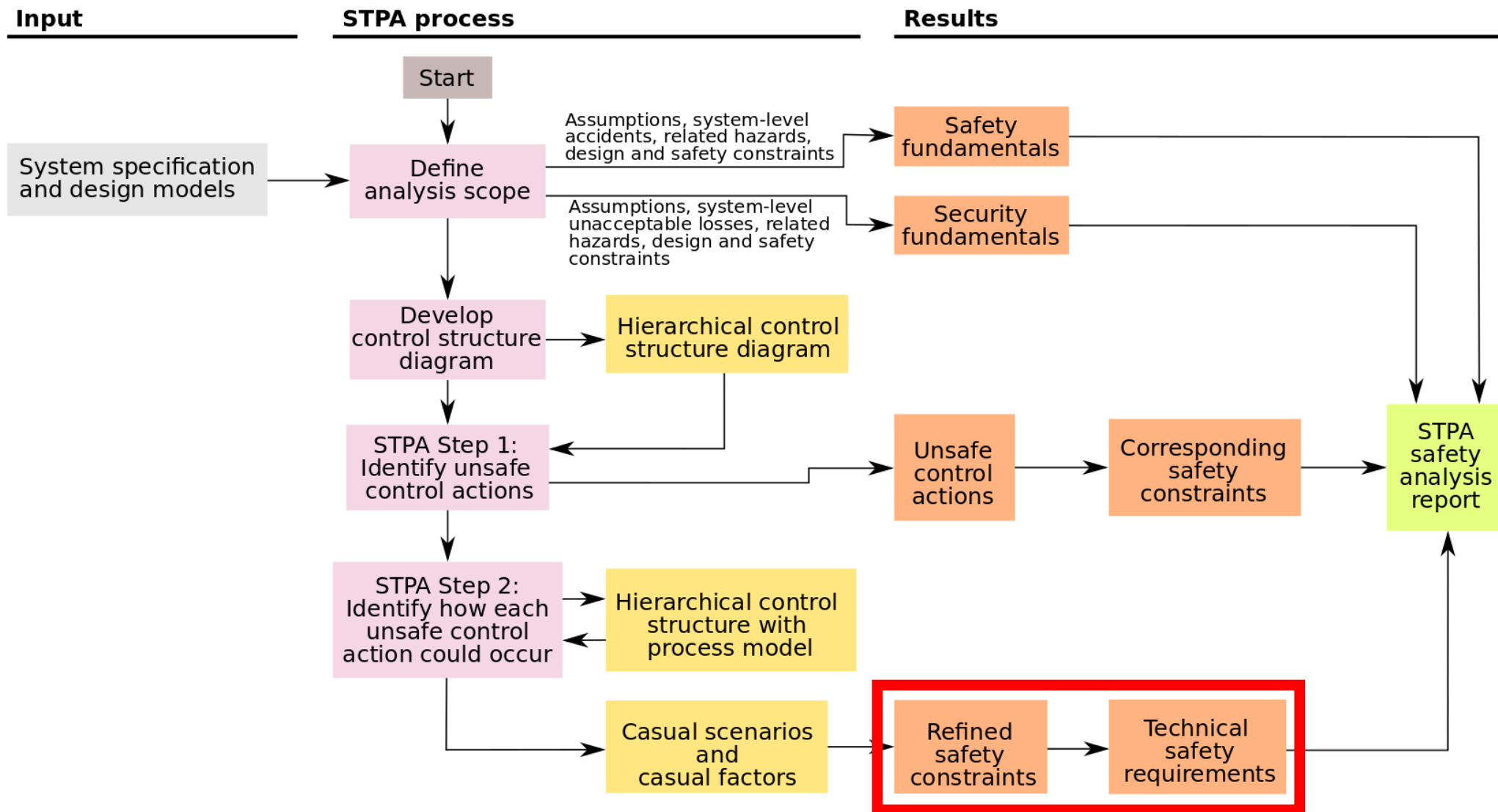
# Lessons learned

➤ *Rationale table:*

- Lists the logic behind the causal factors
- Works as a reference table for further steps

Group	Causal factor	Rationale
Controller (group 1)		
Actuator (group 2)		
Controlled process (group 3)		
B6/B7 Sensors (group 4)		







# Lessons learned

- *Technical safety requirements:*

Trade off between too specific and too generic to allow some flexibility for the designer

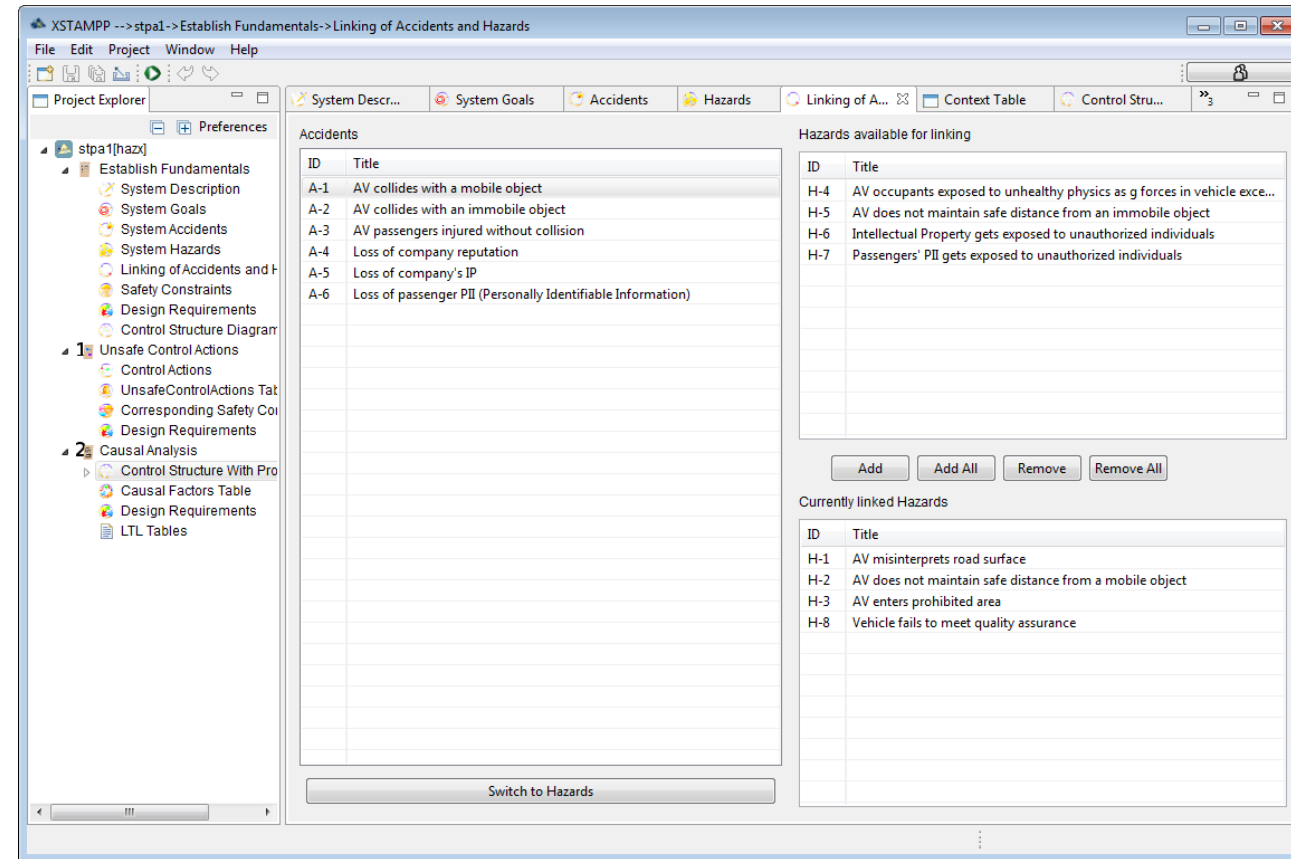
- *Gap analysis:*

Using a generic approach — more extensive applications possible



# Additional Lessons

- *Residual risks*: Some risks which are present in our system that can be accepted.
- *XSTAMPP Experiment*: Tried XSTAMPP tool (version 2.5.0) but abandoned due to inflexibility



# Threats to validity of our analysis

- We are neither AEB, L4 experts, nor security experts (*but we are safety experts*)
- We used STPA for the first time (*but we have experience with other safety standards*)
- The security analysis is heavy on spoofing, but light on other attacks
- Is the analysis general for AEB or wherever applied?
- No formal verification completed
- No implementation has been done



# Summary

- Analyzed AEB of an L4
- Learned lessons
- Valuable experience
- Applicability

## Future Work:

- Comparative study, comparing the analysis with standard ISO 26262
- Can be expanded to cover the complete functionality of AV potentially







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Thank you! Questions?

[shefali.sharma@uwaterloo.ca](mailto:shefali.sharma@uwaterloo.ca)