

STAP:- Applied to a Slurry Dispenser

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Background :-

- Contracted to fill several sizes of container with a curing slurry.
- Needed a rapid and accurate means of dispensing slurry into the container bodies.
- Filling trolley proposed which fitted under the mixing bowl and delivered a “dose” of uncured slurry into the container body using a volumetric pump.

-There were Issues!

Filling Issues

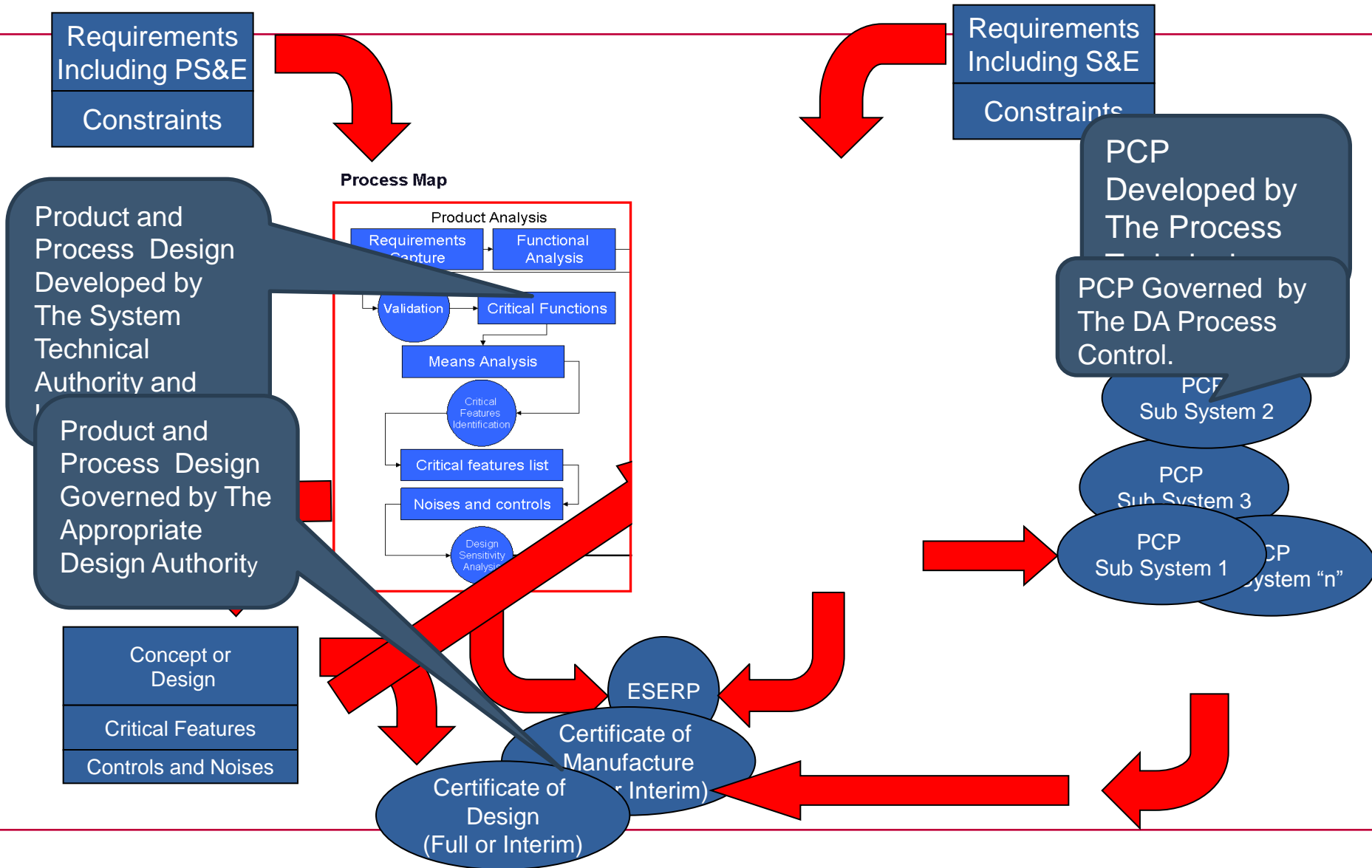
- Dispenser blocked when using a curing formulation.
- Overfills, under fills, and cavities when filling medium sized containers.
- “Safe” vacuum declared when no vacuum existed.
- No correlation between commissioning and first off production material trials.
- Control actions blamed!
- Could STAMP help analyse the situation and provide a solution?
- Current Process Control Plan (PCP) based on the “Process Trilogy”.
 - Process Flow
 - PFMEA
 - PCP
- Very detailed. Some 230 lines.

- Can we see the wood for the trees?

The Design Book

- A Systems Engineering “Design Book” had been collated to look at the filling of Containers and followed the process map from the previous slides.
- What does the design book do?
 - Validates the function requirements deliver our customers requirements set.
 - Identifies the selected means of achieving the design functionality.
 - Identifies the key features within those selected means
 - Identifies the noises and controls within the design space
 - Expresses the means for reducing the noises and applying the controls.
- But we know from bitter experience how we make what we make is important too.....

Design and Process Picture



Computer Control.....Control taken for granted?

- Reaction of the team to questioning at review was “Don’t worry about that, it’s all computer controlled!”
- My questions were as follows :-
 - What are we controlling?
 - How are we controlling it?
 - What happens when the control actions go wrong?
 - Are we controlling the right things?
 - Is there anything missing?
- Where do we start?

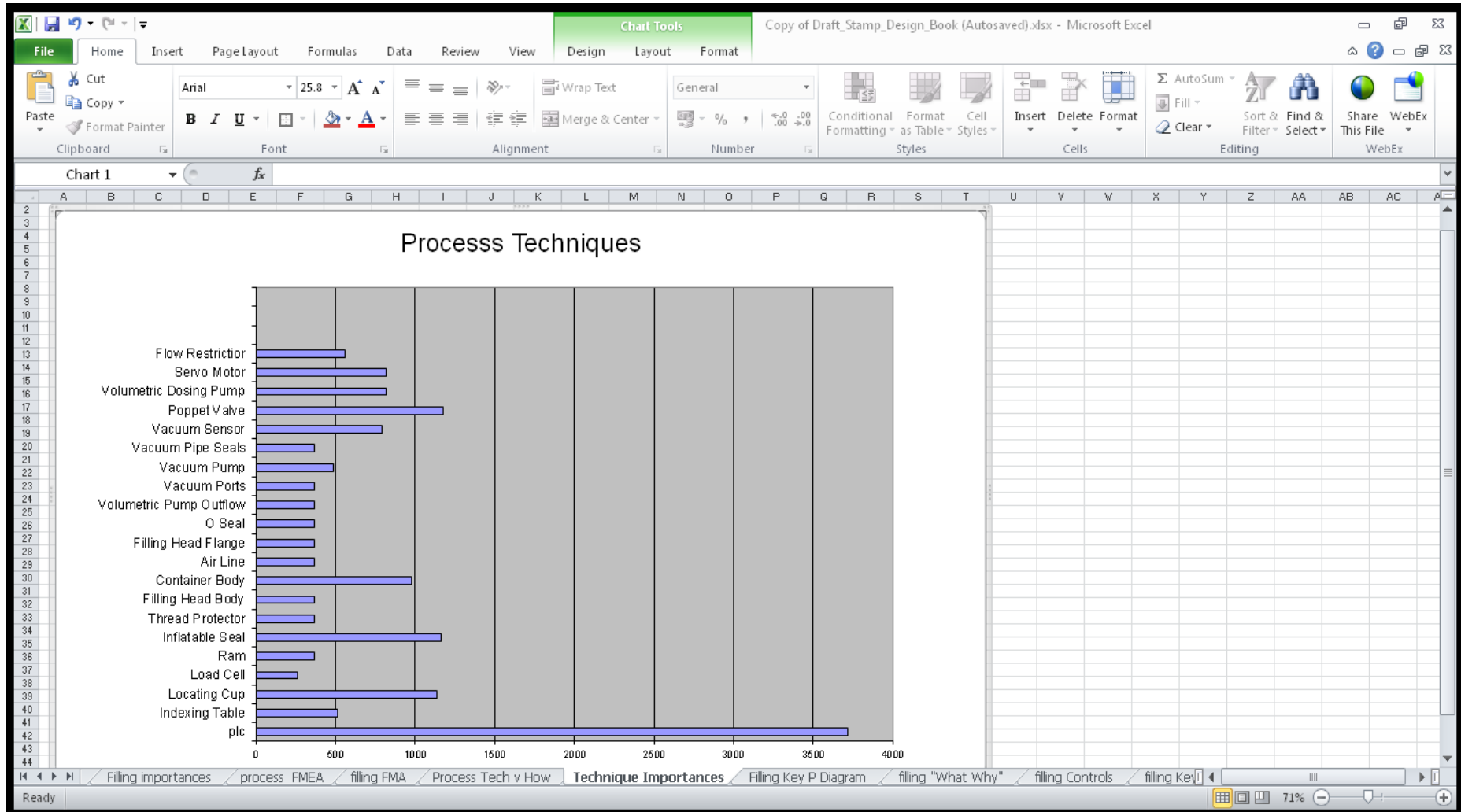
Filling the Container

- Develop a process flow map for the filling process :- Describe as functions.
- Assign means of achieving those functions and explore the relationship between them.

The screenshot shows an Excel spreadsheet titled 'Copy of Draft_Stamp_Design_Book (Autosaved).xlsx'. The spreadsheet is a process feature matrix with the following structure:

- Columns (Means):** Importance, plc, Indesing Table, Locating Cup, Load Cell, Ram, Inflatable Seal, Thread Protector, Filling Head Body, Container Body, Air Line, Filling Head Flange, O Seal, Volumetric Pump Outflow, Vacuum Ports, Vacuum Pump, Vacuum Pipe Seals, Vacuum Sensor, Poppet Valve, Volumetric Dosing Pump, Servo Motor, Flow Restrictor.
- Rows (Functions):** Process Functionality, Locate Container, Record Tare Weight, Index Container, Raise to filling position, Inflate seal, Apply Vacuum, System Checks for vac, Confirm OK, Open Poppet Valve, Volumetric pump activates, Dispense explosive, Stop Dispense, Poppet valve close, Recharge Volumetric pump, Release vac, Lower Container, Index, Check weigh.
- Matrix Content:** A grid of cells containing numerical values (e.g., 3, 9, 0) representing the relationship between functions and means. Some cells are highlighted in red.
- Summary Row (Row 27):** 3714, 510, 1137, 253, 367, 1161, 367, 367, 377, 366, 366, 366, 366, 483, 366, 734, 1174, 815, 815, 556, 0, 0, 0.
- Target/Benchmark/Value Row (Rows 28-30):** Target, Benchmark, Ideal Value.

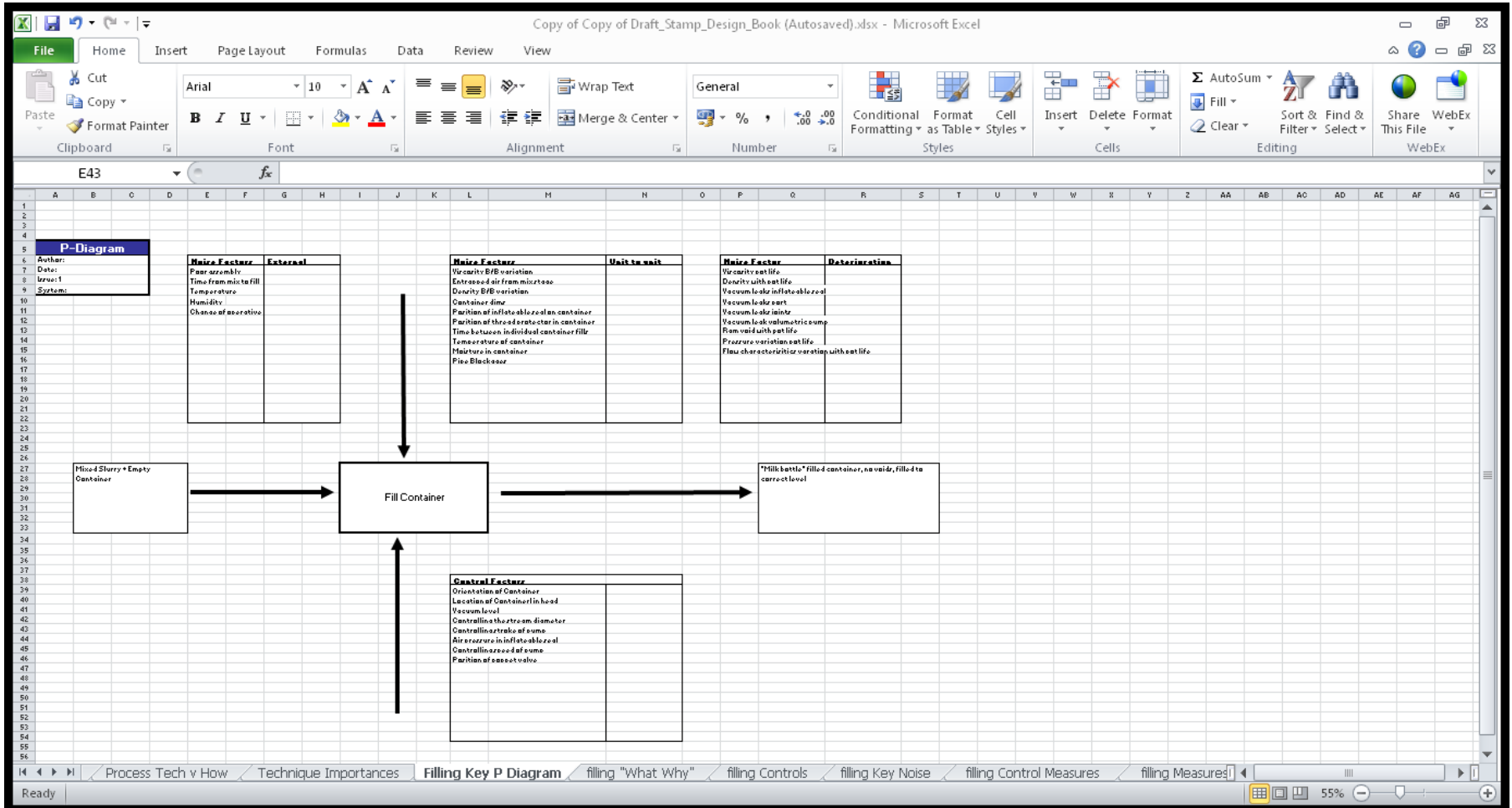
Assess Critical Functions



Noises and controls.

- There are actions in our filling process which we need to control.
- There are also noises from the outside world which affect these control actions.
- We need to know where these noises impinge.
- Enter the what / why table.
- The first stage in it's construction is the development of a parameter diagram. This defines the control space and lists the noises and controls.
- Noises are categorised as unit to unit, deterioration an external.

P-diagram

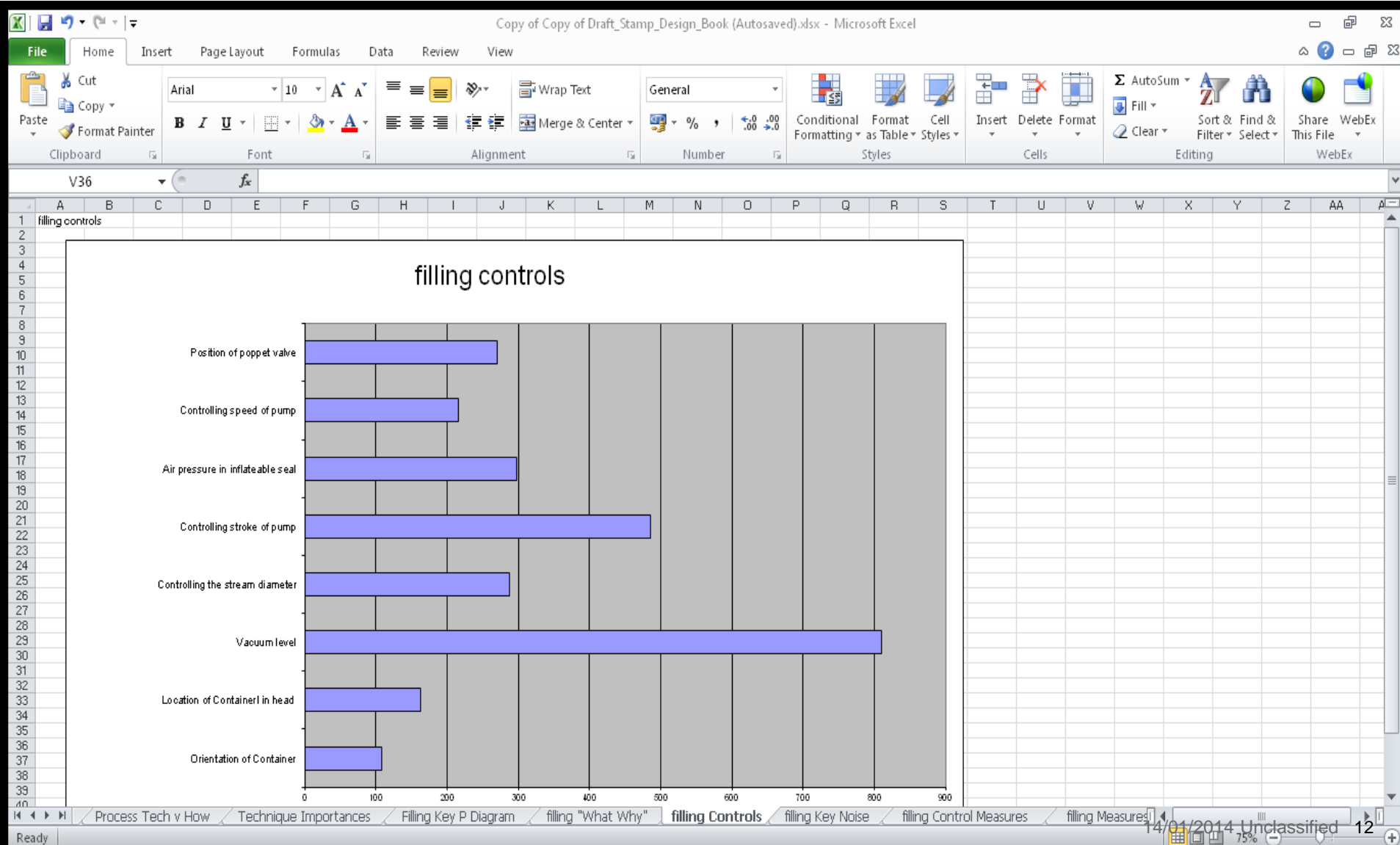


What why table.

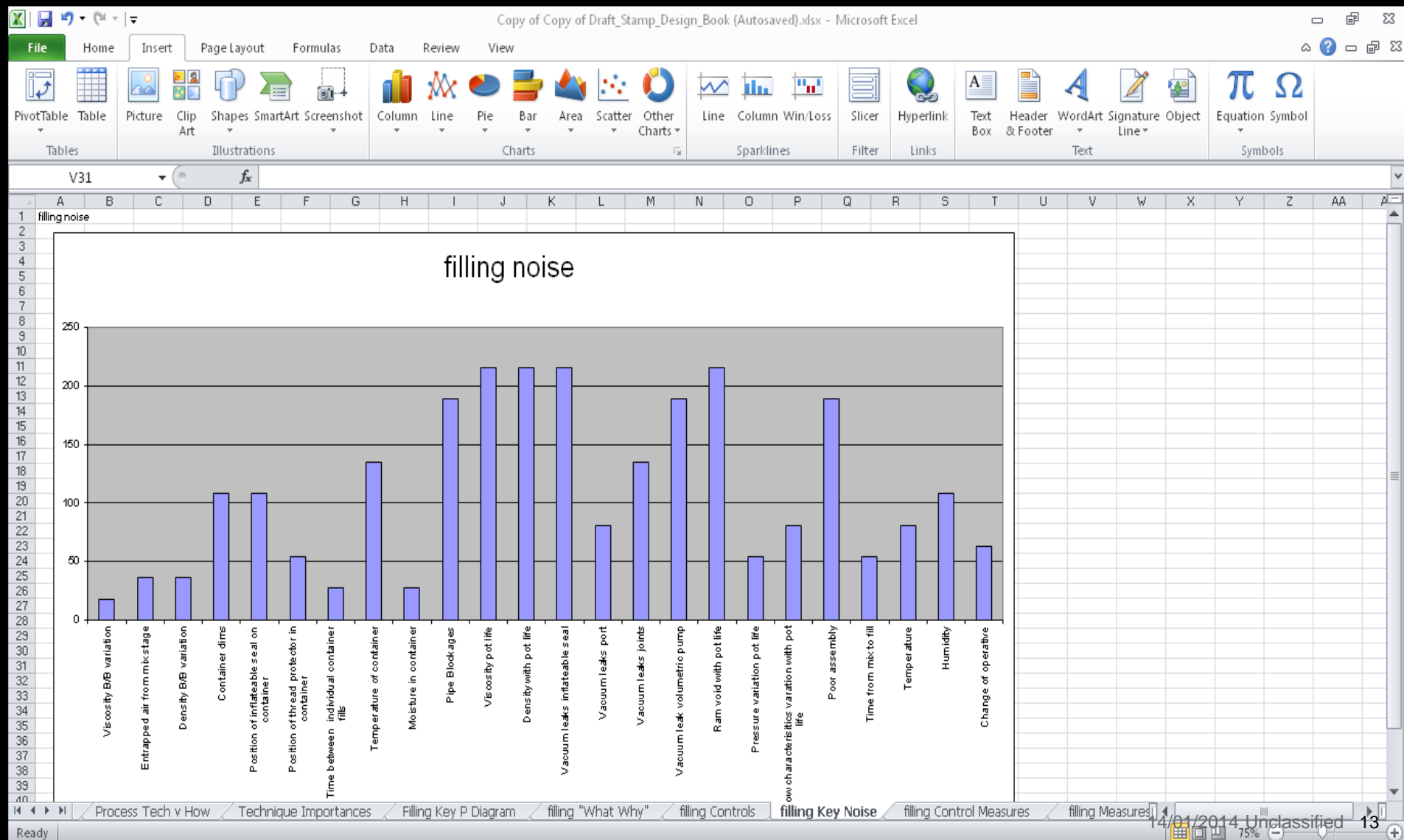
- This is developed into the What Why table where the relationships between noises and controls are explored.

| | | NOISE FACTORS | | | | | | | | | | | | | | | | | | | | Relative importance of noise in meeting performance | | | | | |
|---------------------------------|---|-------------------------|------------------------------|-----------------------|----------------|--|---|---|--------------------------|-----------------------|----------------|--------------------|-----------------------|------------------------------|-------------------|---------------------|-----------------------------|------------------------|-----------------------------|--|---------------|---|-------------|----------|---------------------|----|-----|
| Performance Characteristics Ys: | Weighting of design control parameter | Unit to Unit Variation | | | | | | | | | | Deterioration | | | | | | | External | | | | | | | | |
| | | Mfg | Mfg | Mfg | Mfg | Mfg | Mfg | Mfg | Mfg | Mfg | Mfg | Mfg | Mfg | Mfg | Mfg | Mfg | Mfg | Mfg | Mfg | Human | Environment | Environment | Environment | Human | Total | | |
| | Design control parameters | Viscosity/BIB variation | Entrapped air from mix stage | Density/BIB variation | Container dims | Position of inflatable seal on container | Position of thread protector in container | Time between individual container fills | Temperature of container | Moisture in container | Pipe Blockages | Viscosity pot life | Density with pot life | Vacuum leaks inflatable seal | Vacuum leaks port | Vacuum leaks joints | Vacuum leak volumetric pump | Ram void with pot life | Pressure variation pot life | Flow characteristics variation with pot life | Poor assembly | Time from mix to fill | Temperature | Humidity | Change of operative | | |
| Filling Container | Orientation of Container | 9 | | | 9 | 9 | | | | | | | | 9 | 9 | | | | | | | | | | | 12 | 108 |
| | Location of Container in head | 9 | | | 9 | 9 | | | | | | | | 9 | 9 | | | | | | | | | | | 18 | 162 |
| | Vacuum level | 9 | | | 9 | 9 | 9 | | | | | | | 9 | 9 | 9 | 9 | 9 | 9 | 9 | | | | 9 | 9 | 90 | 810 |
| | Controlling the stream diameter | 3 | 3 | 9 | 9 | | | | | | | 9 | 9 | | | | | 9 | 9 | 9 | 9 | | | | 3 | 96 | 288 |
| | Controlling stroke of pump | 9 | | | | | | | | | | 9 | 9 | | | | | 9 | 9 | 9 | | | | | | 54 | 486 |
| | Air pressure in inflatable seal | 9 | | | 9 | 9 | 9 | | 9 | | | | | 9 | | | | | | 9 | | | | | 3 | 33 | 297 |
| | Controlling speed of pump | 3 | 3 | 3 | 3 | | | | | | | 9 | 9 | | | | 9 | 9 | 9 | 9 | | | | | | 72 | 216 |
| | Position of poppet valve | 9 | | | | | | | | | 9 | 9 | 9 | | | | | | | 3 | | | | | | 30 | 270 |
| | Relative importance of noise factor: | 18 | 36 | 36 | 108 | 108 | 54 | 27 | 135 | 27 | 189 | 216 | 216 | 216 | 81 | 135 | 189 | 216 | 54 | 81 | 189 | 54 | 81 | 108 | 63 | | |
| | Team: | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | Date completed: | | | | | | | | | | | | | | | | | | | | | | | | | | |

Relative Importance of Controls



Relative Importance of Noises

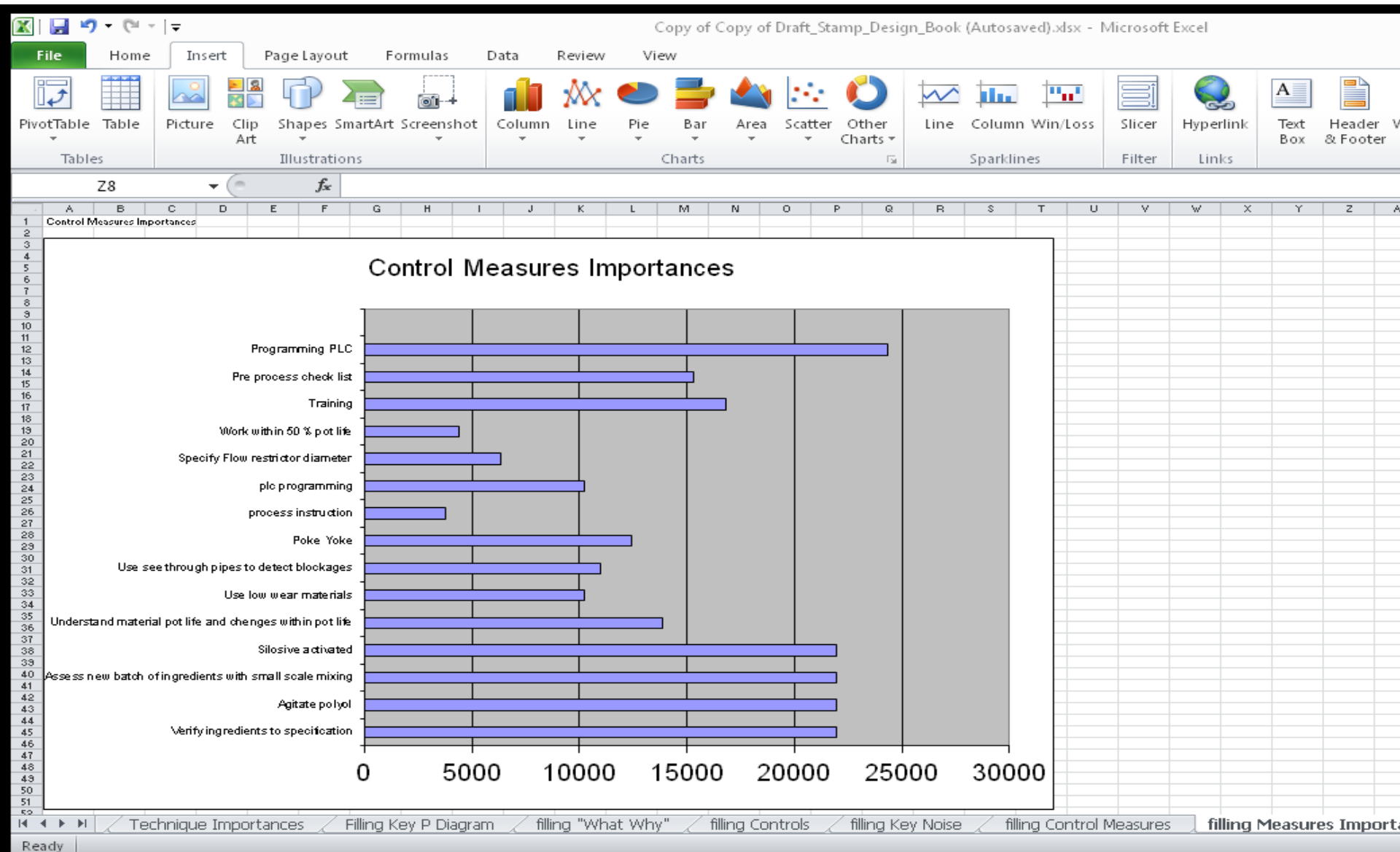


Controls.

- Now in a review I want to see the means of control we are going to exercise.

| | | Operational assessment | | | | | Process Controls | | | | | | | | | | | | | | |
|----------------------------|---------------|---------------------------------|--------|----------|------------|-------|-------------------------------------|----------------|---|--------------------|--|------------------------|---|-----------|---------------------|-----------------|----------------------------------|--------------------------|----------|------------------------|-----------------|
| | | manufacturing controls and Aids | | | | | Verify ingredients to specification | Agitate polyol | Assess new batch of ingredients with small scale mixing | Silosive activated | Understand material pot life and changes within pot life | Use low wear materials | Use see through pipes to detect blockages | Poke Yoke | process instruction | plc programming | Specify Flow restrictor diameter | Work within 50% pot life | Training | Pie process check list | Programming PLC |
| | | Difficulty | Impact | Severity | Occurrence | RPN | | | | | | | | | | | | | | | |
| Process parameters | Target Values | | | | | | | | | | | | | | | | | | | | |
| Entrapped Air from mixer | | 2 | 9 | 9 | 5 | 810 | 3 | 3 | 3 | 3 | 3 | | | 1 | | | | | | | 3 |
| Viscosity from Mixer | | 5 | 5 | 5 | 5 | 625 | 3 | 3 | 3 | 3 | 3 | | | 1 | | | | | | | 3 |
| Density from mixer | | 5 | 5 | 5 | 5 | 625 | 3 | 3 | 3 | 3 | 3 | | | 1 | | | | | | | 3 |
| Vacuum level | | 2 | 9 | 9 | 7 | 1134 | 3 | 3 | 3 | 3 | 3 | 9 | 9 | 1 | 9 | | | 9 | | | 3 |
| Stroke of pump | | 1 | 5 | 5 | 1 | 25 | | | | 3 | | | | 1 | | 3 | | | | | 3 |
| Stream diameter from pump | | 1 | 6 | 6 | 1 | 36 | | | | 3 | | | | 1 | | 3 | | | | | 3 |
| Assembly of trolley | | 5 | 5 | 5 | 2 | 250 | | | | | | | 3 | 1 | | | | 3 | | | 3 |
| rate of delivery | | 2 | 7 | 7 | 2 | 196 | | | | | | | | 1 | | 3 | | | | | 3 |
| Delivery of correct volume | | 2 | 2 | 3 | 7 | 84 | | | | | | 9 | | 1 | | 3 | | | | | 3 |
| Achieve good clean down | | 3 | 9 | 9 | 2 | 486 | | | | | | | | | | 3 | 9 | | | | 3 |
| | | | | | | 21942 | 21942 | 21942 | 21942 | 13863 | 10206 | 10962 | 12456 | 3785 | 10206 | 6321 | 4374 | 16830 | 15303 | 24315 | 0 |

Control 2



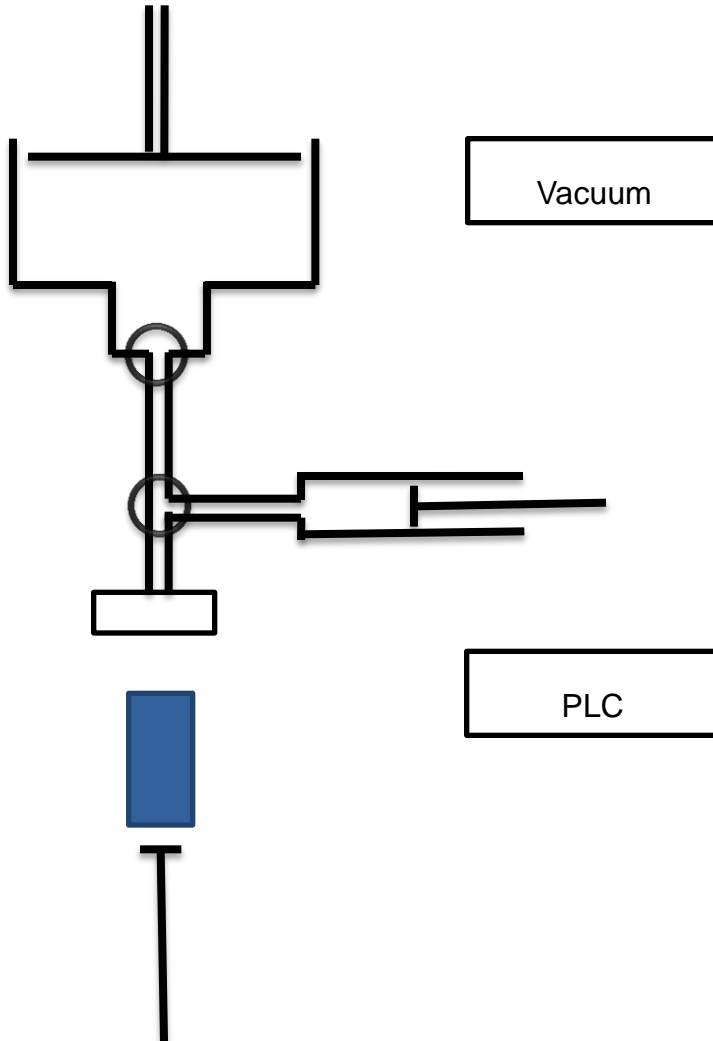
Computer Control.....Control taken for granted?

- Remember this slide?
 - Reaction of the team to questioning at review was “Don’t worry about that, it’s all computer controlled!”
 - My questions were as follows
 - “What are we controlling?”
 - How are we controlling it?
 - What happens when the control actions go wrong?”
 - “Are we controlling the right things?”
 - “Is there anything missing?”
 - Where do we start?
- Well at least we know what we are controlling via the PLC. Bur how are we doing it and is there anything missing.

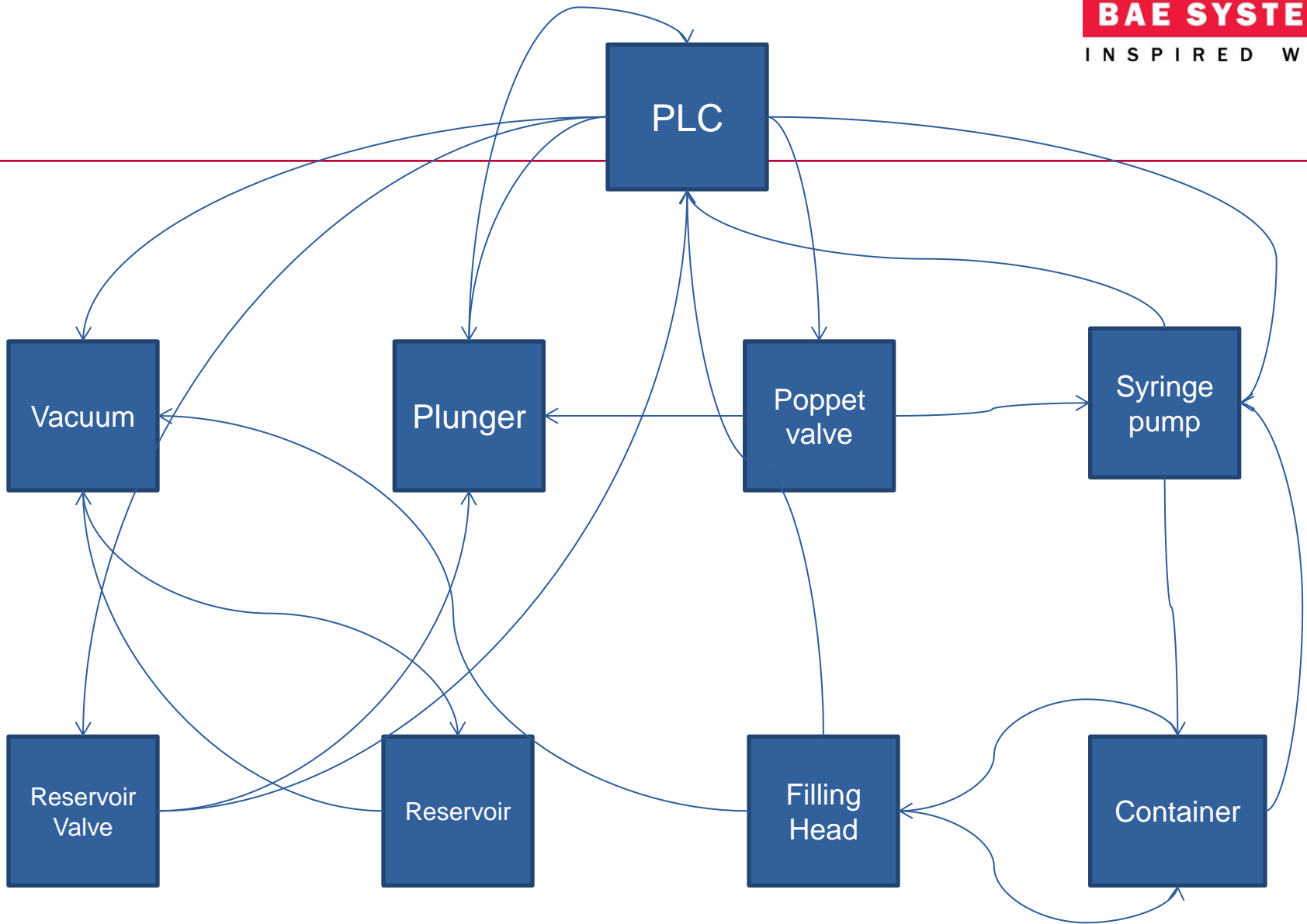
Develop the control “map”.

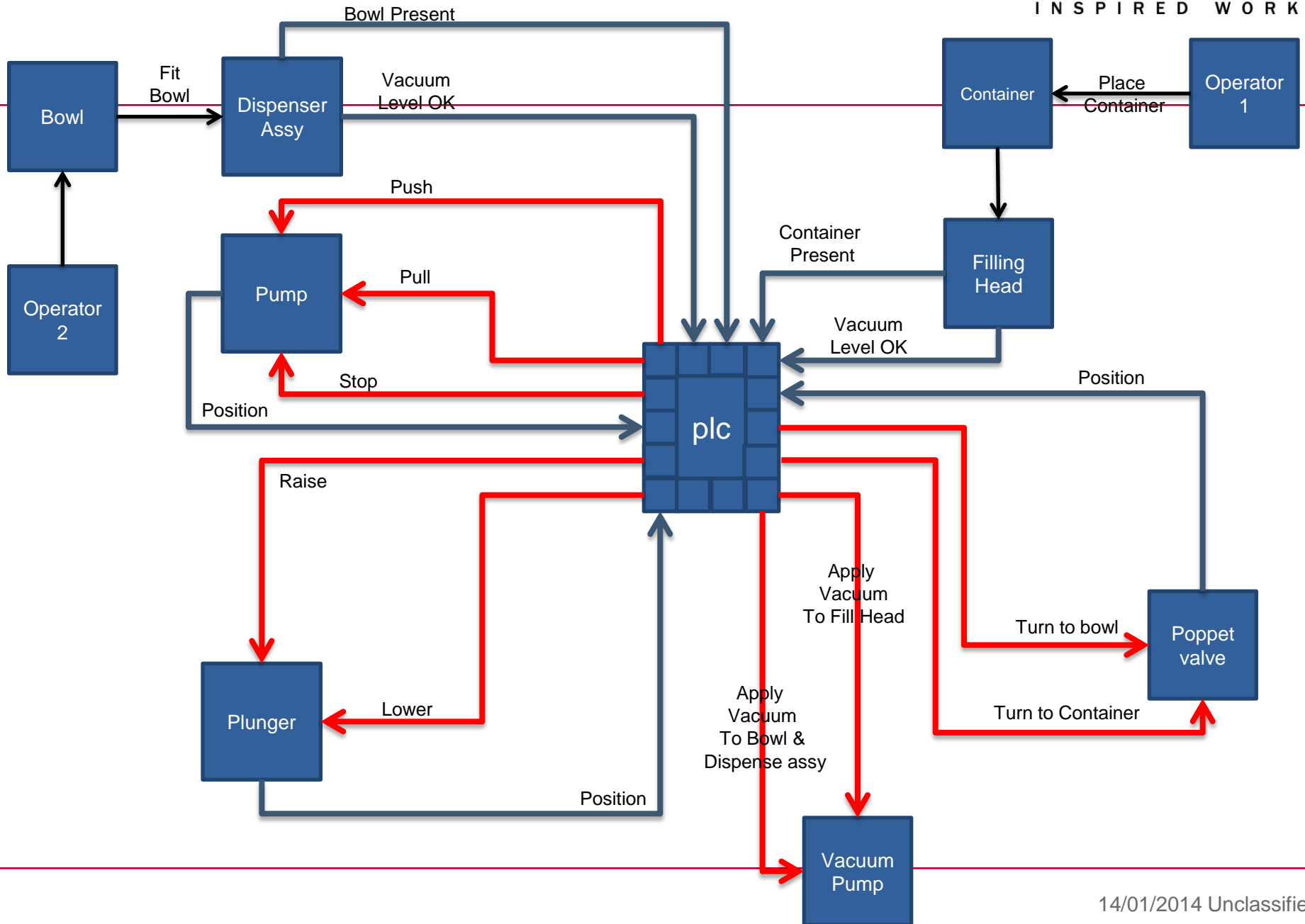
- Schematic.
 - Pen picture of the operation of the dispenser.
- Relationship Network.
 - How do all the component parts of this device come together to deliver the product.
- Command network.
 - How to we tell the component parts when to perform their function
 -And when to stop.

Schematic



1. Bowl to plunger
2. Vac applied to bowl
3. Container raised to header
4. Vac applied to system
5. Poppet valve to bowl
6. Bowl valve open
7. Piston withdraws
8. Piston stop
9. Poppet valve to Container
10. Piston pushes
11. Piston stops
12. Poppet valve to bowl
13. Container lowers
14. Container removed
15. Container reload





What are The Top Level, System Accident Scenarios?

Design Requirements

| | |
|----------------------------------|---|
| System Level Accident | Loss of capability due to Catastrophic Failure |
| System Level Hazard | Catastrophic Failure |
| System level safety constraints. | No Catastrophic explosion = No cavities = Correct filling |

Process Requirements

| | |
|----------------------------------|---|
| System Level Accident | Loss of capability due to Catastrophic Failure in facility |
| System Level Hazard | Catastrophic Failure during filling |
| System level safety constraints. | No leaks, No Blockages, Slurry within pot life, Effective clean down, No Contamination. |

Analysis

- We then discussed our command actions in the control system one by one, asking the questions.
 - What happens if.....
 - Command not given.
 - Unsafe command given.
 - Too long.
 - Too short.
 - Too late.
 - Too Early.
- We recorded any actions that would resolve any issues. Tried to be consistent so we could ascertain if one action would hit many issues.
- Also included an index according to the probability, severity and of ability to detect (on the current design) the consequences of issues stemming from the above.

Analysis.

Analysis 2

| Command / Report | From | To | Action | Comments | Prob | Sev | Det | RPN | Action |
|------------------------------|---------------------|--|----------------|---|------|-----|-----|-----|--|
| System Level Accident | | Loss of capability, Catastrophic Failure | | | | | | | |
| System Level Hazard | | Unsafe Container | | | | | | | |
| System level safety | | No Catastrophic Failure = No cavities = Correct filling | | | | | | | |
| Vacuum Level OK | Bowl Dispenser Assy | PLC | Safe not given | Process does not start. No Vacuum. | 1 | 1 | 1 | 1 | |
| | | | Unsafe given | Vac displayed as good when it is not. System starts with material not under vacuum | 3 | 9 | 9 | 243 | Check all potential blockage points and position of vacuum sensors in the system |
| | | | Too early | Vacuum may not be at required level | 3 | 9 | 3 | 81 | |
| | | | Too late | Delay in system start | 1 | 1 | 1 | 1 | |
| | | | Too long | Delay in system start | 1 | 1 | 1 | 1 | |
| | | | Too Short | Vacuum may not be at required level | 1 | 9 | 3 | 27 | |
| Bowl Present | Bowl Dispenser Assy | PLC | Safe not given | System does not start even though equipment is | 1 | 1 | 1 | 1 | |
| | | | Unsafe given | System could start, Vacuum not present could override this situation | 1 | 9 | 1 | 9 | Bowl not present signal should inhibit vacuum function. Thus trigger alarm. |
| | | | Too early | System could start, Vacuum not present could override this situation | 1 | 9 | 1 | 9 | |
| | | | Too late | Delay in system start | 1 | 1 | 1 | 1 | |
| | | | Too long | Delay in system start | 1 | 1 | 1 | 1 | |
| | | | Too Short | System could start, Vacuum not present could override this situation | 1 | 9 | 1 | 9 | |
| Push | PLC | Pump | Safe not given | System stalls and comes under pressure from plunger. Could get system blockages. Could get "un- | 3 | 9 | 1 | 27 | Need to synchronise plunger push with pump pull |
| | | | Unsafe given | Could overflow Container, could deliver material not vacuumed | 9 | 9 | 3 | 243 | No vacuum condition needs to override pump push |
| | | | Too early | Short dose delivered | 3 | 9 | 3 | 81 | Need "detect level" function. |
| | | | Too late | Delay in system start | 1 | 1 | 1 | 1 | |
| | | | Too long | Could overflow Container, could deliver material not vacuumed | 9 | 9 | 3 | 243 | Need "detect level" function. |
| | | | Too Short | Short dose delivered | 3 | 9 | 3 | 81 | Need "detect level" function. |
| Pull | PLC | Pump | Safe not given | Delay in system start | 1 | 1 | 1 | 1 | |
| | | | Unsafe given | Filling of un-vacuumed product | 3 | 9 | 9 | 243 | vacuum unsafe condition needs to inhibit pump pull |
| | | | Too early | Filling of un-vacuumed product | 3 | 9 | 9 | 243 | vacuum unsafe condition needs to inhibit pump pull |
| | | | Too late | Delay in system start | 1 | 1 | 1 | 1 | |
| | | | Too long | Overdose Container | 3 | 9 | 1 | 27 | Need "detect level" function. |
| | | | Too Short | under-dose Container | 3 | 3 | 1 | 9 | Need "detect level" function. |
| Stop | PLC | Pump | Safe not given | wrong dose drawn into pump. Wrong dose delivered | 3 | 9 | 1 | 27 | Need "detect level" function. |
| | | | Unsafe given | wrong dose drawn into pump. Wrong dose delivered | 3 | 9 | 1 | 27 | Need "detect level" function. |
| | | | Too early | wrong dose drawn into pump. Wrong dose delivered | 3 | 9 | 1 | 27 | Need "detect level" function. |
| | | | Too late | wrong dose drawn into pump. Wrong dose delivered | 3 | 9 | 1 | 27 | Need "detect level" function. |
| | | | Too long | wrong dose drawn into pump. Wrong dose delivered | 3 | 9 | 1 | 27 | Need "detect level" function. |
| | | | Too Short | wrong dose drawn into pump. Wrong dose delivered | 3 | 9 | 1 | 27 | Need "detect level" function. |
| Report Position | Pump | PLC | Safe not given | wrong dose drawn into pump. Wrong dose delivered | 3 | 9 | 1 | 27 | Need "detect level" function. |
| | | | Unsafe given | wrong dose drawn into pump. Wrong dose delivered | 3 | 9 | 1 | 27 | Need "detect level" function. |
| | | | Too early | wrong dose drawn into pump. Wrong dose delivered | 3 | 9 | 1 | 27 | Need "detect level" function. |
| | | | Too late | wrong dose drawn into pump. Wrong dose delivered | 3 | 9 | 1 | 27 | Need "detect level" function. |
| | | | Too long | Delay in system start | 1 | 1 | 1 | 1 | |
| | | | Too Short | Delay in system start | 1 | 1 | 1 | 1 | |
| Raise | PLC | Plunger | Safe not given | Delay in system start | 1 | 1 | 1 | 1 | |
| | | | Unsafe given | Release of vacuum | 3 | 9 | 1 | 27 | Interlock with vacuum signal |
| | | | Too early | Release of vacuum | 3 | 9 | 1 | 27 | Interlock with vacuum signal |
| | | | Too late | Filling delay | 1 | 1 | 1 | 1 | |
| | | | Too long | Delay in system start | 1 | 1 | 1 | 1 | |
| | | | Too Short | Delay in system start | 1 | 1 | 1 | 1 | |

Analysis 3

| Command / Report | From | To | Action | Comments | Prob | Sev | Det | RPN | Action |
|--------------------------------------|---|--------------|----------------|---|------|-----|-----|-----|--|
| System Level Accident | Loss of capability, Catastrophic Failure | | | | | | | | |
| System Level Hazard | Unsafe Container | | | | | | | | |
| System level safety constraints: | No Catastrophic Failure = No cavities = Correct filling | | | | | | | | |
| Vacuum Level OK | Bowl Dispenser Assy | PLC | Unsafe given | Vac displayed as good when it is not. System starts with material not under vacuum | 3 | 3 | 3 | 243 | Check all potential blockage points and position of vacuum sensors in the system |
| Push | PLC | Pump | Unsafe given | Could overflow Container, could deliver material not vacuumed | 3 | 3 | 3 | 243 | No vacuum condition needs to override pump push |
| Push | PLC | Pump | Too long | Could overflow Container, could deliver material not vacuumed | 3 | 3 | 3 | 243 | Need "detect level" function. |
| Pull | PLC | Pump | Unsafe given | Filling of un-vacuumed product | 3 | 3 | 3 | 243 | vacuum unsafe condition needs to inhibit pump pull |
| Pull | PLC | Pump | Too early | Filling of un-vacuumed product | 3 | 3 | 3 | 243 | vacuum unsafe condition needs to inhibit pump pull |
| Vacuum Level OK | Filling Head | PLC | Unsafe given | Vac displayed as good when it is not. System starts with material not under vacuum | 3 | 3 | 3 | 243 | Check all potential blockage points and position of vacuum sensors in the system |
| Apply Vacuum To Fill Head | PLC | Vac Pump | Too early | Suck from atmosphere inclusion of moisture | 3 | 3 | 3 | 243 | Check all potential blockage points and position of vacuum sensors in the system |
| Apply Vacuum To Fill Head | PLC | Vac Pump | Too Short | Vacuum may not be at required level | 3 | 3 | 3 | 243 | Check all potential blockage points and position of vacuum sensors in the system |
| Apply Vacuum To Bowl & Dispense assy | PLC | Vac Pump | Too early | Suck from atmosphere inclusion of moisture | 3 | 3 | 3 | 243 | Check all potential blockage points and position of vacuum sensors in the system |
| Apply Vacuum To Bowl & Dispense assy | PLC | Vac Pump | Too Short | Vacuum may not be at required level | 3 | 3 | 3 | 243 | Check all potential blockage points and position of vacuum sensors in the system |
| Vacuum Level OK | Bowl Dispenser Assy | PLC | Too early | Vacuum may not be at required level | 3 | 3 | 3 | 81 | |
| Push | PLC | Pump | Too early | Short dose delivered | 3 | 3 | 3 | 81 | Need "detect level" function. |
| Push | PLC | Pump | Too Short | Short dose delivered | 3 | 3 | 3 | 81 | Need "detect level" function. |
| Turn to Container | PLC | Poppet Valve | Unsafe given | Partial fill or fill of non vacuumed product | 3 | 3 | 3 | 81 | |
| Report Position | Poppet Valve | PLC | Safe not given | Delivery back into bowl. System stops or Partial fill or fill of non vacuumed product | 3 | 3 | 3 | 81 | Position needs to be interlocked with vacuum and pump push |
| Report Position | Poppet Valve | PLC | Unsafe given | Delivery back into bowl. System stops or Partial fill or fill of non vacuumed product | 3 | 3 | 3 | 81 | Position needs to be interlocked with vacuum and pump push |
| Report Position | Poppet Valve | PLC | Too early | Delivery back into bowl. System stops or Partial fill or fill of non vacuumed product | 3 | 3 | 3 | 81 | Position needs to be interlocked with vacuum and pump push |
| Report Position | Poppet Valve | PLC | Too late | Delivery back into bowl. System stops or Partial fill or fill of non vacuumed product | 3 | 3 | 3 | 81 | Position needs to be interlocked with vacuum and pump push |
| Vacuum Level OK | Filling Head | PLC | Too early | Vac displayed as good when it is not. System starts with material not under vacuum | 3 | 3 | 3 | 81 | Check all potential blockage points and position of vacuum sensors in the system |
| Vacuum Level OK | Filling Head | PLC | Safe not given | Process does not start. No Vacuum. | 3 | 3 | 1 | 81 | |
| Vacuum Level OK | Bowl Dispenser Assy | PLC | Too Short | Vacuum may not be at required level | 1 | 3 | 3 | 27 | Check all potential blockage points and position of vacuum sensors in the system |
| Push | PLC | Pump | Safe not given | System stalls and comes under pressure from plunger. Could get system blockages. Could get "un-mixing". | 3 | 3 | 1 | 27 | Need to synchronize plunger push with pump pull |
| Pull | PLC | Pump | Too long | Overflow Container | 3 | 3 | 1 | 27 | Need "detect level" function. |
| Stop | PLC | Pump | Safe not given | wrong dose drawn into pump. Wrong dose delivered | 3 | 3 | 1 | 27 | Need "detect level" function. |
| Stop | PLC | Pump | Unsafe given | wrong dose drawn into pump. Wrong dose delivered | 3 | 3 | 1 | 27 | Need "detect level" function. |
| Stop | PLC | Pump | Too early | wrong dose drawn into pump. Wrong dose delivered | 3 | 3 | 1 | 27 | Need "detect level" function. |
| Stop | PLC | Pump | Too late | wrong dose drawn into pump. Wrong dose delivered | 3 | 3 | 1 | 27 | Need "detect level" function. |
| Stop | PLC | Pump | Too long | wrong dose drawn into pump. Wrong dose delivered | 3 | 3 | 1 | 27 | Need "detect level" function. |
| Stop | PLC | Pump | Too Short | wrong dose drawn into pump. Wrong dose delivered | 3 | 3 | 1 | 27 | Need "detect level" function. |
| Report Position | Pump | PLC | Safe not given | wrong dose drawn into pump. Wrong dose delivered | 3 | 3 | 1 | 27 | Need "detect level" function. |
| Report Position | Pump | PLC | Unsafe given | wrong dose drawn into pump. Wrong dose delivered | 3 | 3 | 1 | 27 | Need "detect level" function. |
| Report Position | Pump | PLC | Too early | wrong dose drawn into pump. Wrong dose delivered | 3 | 3 | 1 | 27 | Need "detect level" function. |
| Report Position | Pump | PLC | Too late | wrong dose drawn into pump. Wrong dose delivered | 3 | 3 | 1 | 27 | Need "detect level" function. |
| Raise | PLC | Plunger | Unsafe given | Release of vacuum | 3 | 3 | 1 | 27 | Interlock with vacuum signal |
| Raise | PLC | Plunger | Too early | Release of vacuum | 3 | 3 | 1 | 27 | Interlock with vacuum signal |
| Lower | PLC | Plunger | Too early | Clash with bowl, increase in entrained air | 1 | 3 | 3 | 27 | Interlock with plunger position indicator |
| Turn to bowl | PLC | Poppet Valve | Unsafe given | delivery back into bowl. System stops | 3 | 3 | 1 | 27 | Interlock with plunger push |
| Turn to Container | PLC | Poppet Valve | Too early | Partial fill or fill of non vacuumed product | 3 | 3 | 3 | 27 | Interlock with plunger push |
| Turn to Container | PLC | Poppet Valve | Too Short | Partial fill or fill of non vacuumed product | 3 | 3 | 3 | 27 | Interlock with plunger push |
| Container Present | Filling Head | PLC | Unsafe given | Spill of Slurry | 3 | 3 | 1 | 27 | Container presence interlocked to pump and poppet valve |
| Container Present | Filling Head | PLC | Too early | Spill of Slurry | 3 | 3 | 1 | 27 | Container presence interlocked to pump and poppet valve |

Analysis 4

| | A | B | C | D | E | F | G | H | I | J | K | L | M | N |
|----|---|---|--|--------------|---------------|--|-------------|------------|------------|------------|--|---|---|---|
| 1 | | | | | | | | | | | | | | |
| 2 | | | | | | | | | | | | | | |
| 3 | | | | | | | | | | | | | | |
| 4 | | System Level Accident | Loss of capability, Catastrophic Failure | | | | | | | | | | | |
| 5 | | System Level Hazard | Unsafe Container | | | | | | | | | | | |
| 6 | | System level safety constraints. | No Catastrophic Failure = No cavities = Correct filling | | | | | | | | | | | |
| 7 | | | | | | | | | | | | | | |
| 8 | | Command / Report | From | To | Action | Comments | Prob | Sev | Det | RPN | Action | | | |
| 9 | | Bowl Present | Bowl Dispenser Assy | PLC | Unsafe given | System could start, Vacuum not present could override this situation | 1 | 9 | 1 | 9 | Bowl not present signal should inhibit vacuum function. Thus trigger alarm. | | | |
| 10 | | Vacuum Level OK | Bowl Dispenser Assy | PLC | Unsafe given | Vac displayed as good when it is not. System starts with material not under vacuum | 3 | 9 | 9 | 243 | Check all potential blockage points and position of vacuum sensors in the system | | | |
| 11 | | Vacuum Level OK | Filling Head | PLC | Unsafe given | Vac displayed as good when it is not. System starts with material not under vacuum | 3 | 9 | 9 | 243 | Check all potential blockage points and position of vacuum sensors in the system | | | |
| 12 | | Apply Vacuum To Fill Head | PLC | Vac Pump | Too early | Suck from atmosphere inclusion of moisture | 3 | 9 | 9 | 243 | Check all potential blockage points and position of vacuum sensors in the system | | | |
| 13 | | Apply Vacuum To Fill Head | PLC | Vac Pump | Too Short | Vacuum may not be at required level | 3 | 9 | 9 | 243 | Check all potential blockage points and position of vacuum sensors in the system | | | |
| 14 | | Apply Vacuum To Bowl & Dispense assy | PLC | Vac Pump | Too early | Suck from atmosphere inclusion of moisture | 3 | 9 | 9 | 243 | Check all potential blockage points and position of vacuum sensors in the system | | | |
| 15 | | Apply Vacuum To Bowl & Dispense assy | PLC | Vac Pump | Too Short | Vacuum may not be at required level | 3 | 9 | 9 | 243 | Check all potential blockage points and position of vacuum sensors in the system | | | |
| 16 | | Vacuum Level OK | Filling Head | PLC | Too early | Vac displayed as good when it is not. System starts with material not under vacuum | 3 | 3 | 9 | 81 | Check all potential blockage points and position of vacuum sensors in the system | | | |
| 17 | | Vacuum Level OK | Bowl Dispenser Assy | PLC | Too Short | Vacuum may not be at required level | 1 | 9 | 3 | 27 | Check all potential blockage points and position of vacuum sensors in the system | | | |
| 18 | | Vacuum Level OK | Filling Head | PLC | Too Short | Vacuum may not be at required level | 1 | 9 | 3 | 27 | Check all potential blockage points and position of vacuum sensors in the system | | | |
| 19 | | Apply Vacuum To Fill Head | PLC | Vac Pump | Unsafe given | No vac supplied, Container not evacuated | 3 | 9 | 1 | 27 | Check all potential blockage points and position of vacuum sensors in the system | | | |
| 20 | | Apply Vacuum To Fill Head | PLC | Vac Pump | Too late | Poor vacuum reached | 3 | 9 | 1 | 27 | Check all potential blockage points and position of vacuum sensors in the system | | | |
| 21 | | Apply Vacuum To Fill Head | PLC | Vac Pump | Too long | Delay in system start | 3 | 9 | 1 | 27 | Check all potential blockage points and position of vacuum sensors in the system | | | |
| 22 | | Apply Vacuum To Bowl & Dispense assy | PLC | Vac Pump | Unsafe given | No vac supplied, Container not evacuated | 3 | 9 | 1 | 27 | Check all potential blockage points and position of vacuum sensors in the system | | | |
| 23 | | Apply Vacuum To Bowl & Dispense assy | PLC | Vac Pump | Too late | Poor vacuum reached | 3 | 9 | 1 | 27 | Check all potential blockage points and position of vacuum sensors in the system | | | |
| 24 | | Apply Vacuum To Bowl & Dispense assy | PLC | Vac Pump | Too long | Delay in system start | 3 | 9 | 1 | 27 | Check all potential blockage points and position of vacuum sensors in the system | | | |
| 25 | | Container Present | Filling Head | PLC | Unsafe given | Spill of Slurry | 3 | 9 | 1 | 27 | Container presence interlocked to pump and poppet valve | | | |
| 26 | | Container Present | Filling Head | PLC | Too early | Spill of Slurry | 3 | 9 | 1 | 27 | Container presence interlocked to pump and poppet valve | | | |
| 27 | | Container Present | Filling Head | PLC | Too Short | Spill of Slurry | 3 | 9 | 1 | 27 | Container presence interlocked to pump and poppet valve | | | |
| 28 | | Lower | PLC | Plunger | Too early | Clash with bowl, increase in entrained air | 1 | 9 | 3 | 27 | Interlock with plunger position indicator | | | |
| 29 | | Turn to bowl | PLC | Poppet Valve | Unsafe given | delivery back into bowl. System stops | 3 | 9 | 1 | 27 | Interlock with plunger push | | | |
| 30 | | Turn to Container | PLC | Poppet Valve | Too early | Partial fill or fill of non vacuumed product | 3 | 3 | 3 | 27 | Interlock with plunger push | | | |
| 31 | | Turn to Container | PLC | Poppet Valve | Too Short | Partial fill or fill of non vacuumed product | 3 | 3 | 3 | 27 | Interlock with plunger push | | | |
| 32 | | Raise | PLC | Plunger | Unsafe given | Release of vacuum | 3 | 9 | 1 | 27 | Interlock with vacuum signal | | | |
| 33 | | Raise | PLC | Plunger | Too early | Release of vacuum | 3 | 9 | 1 | 27 | Interlock with vacuum signal | | | |
| 34 | | Push | PLC | Pump | Too long | Could overflow Container, could deliver material not vacuumed | 9 | 9 | 3 | 243 | Need "detect level" function. | | | |
| 35 | | Push | PLC | Pump | Too early | Short dose delivered | 3 | 9 | 3 | 81 | Need "detect level" function. | | | |
| 36 | | Push | PLC | Pump | Too Short | Short dose delivered | 3 | 9 | 3 | 81 | Need "detect level" function. | | | |

Recommendations.

- Re-position vacuum sensors to remove the risk of a false “Vacuum achieved” signal.
- Redesign poppet valve to reduce chance of blockage.
- Insert “Detect full” feature.
- Insert link between plunger and piston so the piston does not try to push against the plunger.

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