



### RAAML COMPLIANT BASED STPA TOOL INTEGRATION AT L3HARRIS TECHNOLOGIES

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## **Brief Overview**





- L3H SAS is undergoing a "Digital Thread" initiative to provide interconnection between pre-production and production artifacts
- L3H SAS is increasingly utilizing MBSE techniques to design system architectures
- STPA has been adopted within L3H SAS as a safety analysis method because it supports the Digital Thread initiative and can be incorporated into a MBSE environment
- OMG recently released (2021) a new standard, Risk Analysis and Assessment Modeling Language, which includes modeling constructs for creating STPA elements within a SysML model.





OMG RISK ANALYSIS AND ASSESSMENT MODELING LANGUAGE



# Initial Problems with Adopting STPA @ L3H SAS

# How do we go from knowing nothing about STPA to knowing something?

A. In-house training module development for general STPA knowledge needs



# STPA is a relatively new technique, How do we include it within company command media?

- A. In-house training module development for general STPA knowledge needs
- B. STPA overview presentations for key leadership and business areas

	Traditional Method (FTA, FMEA, ETA, HAZOP)	Systems Theory Method (STPA)
Hazards	<ul> <li>Component Failures→ Hazards</li> <li>↓ Component Failure Rates→</li></ul>	Unconstrained Behavior <del>s&gt;</del> Hazards     Constrained Behavior <del>s&gt;</del> îSafety
Behaviors	<ul> <li>Restricted to behaviors of HW</li> <li>Behaviors are separate sequential events</li> <li>E1 + E2 + E3</li> </ul>	<ul> <li>Behaviors may be of HW, SW and Human</li> <li>Sequence of behaviors may vary</li> <li>E1</li> </ul>
Usability	<ul> <li>Traceable to model elements</li> <li>MBSE add-ons are available</li> </ul>	Traceable to model elements     STPA is MBSE (Control/Feedback Loops)     Controller     ControlAction     Process
Development Lifecycle	<ul><li>Performed during PDR/CDR</li><li>Findings can be expensive</li></ul>	<ul> <li>Basic models can be developed during concept phase</li> <li>Findings are relatively cheap</li> </ul>





## What tools are we going to use to perform STPA analyses?



- A. In-house training module development for general STPA knowledge needs
- B. STPA overview presentations for key leadership and business areas
- C. Exploration of tooling options to help standardize STPA process approach (this was back in 2019)
  - Toolset A
  - Toolset B
  - Toolset C





- A. In-house training module development for general STPA knowledge needs
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Each option led to a "brick wall"





## Development of the RAAML Compliant STPA Toolset @ L3H SAS

# Development of the RAAML Compliant STPA Toolset @ L3H SAS – Discovery Phase







Discovery

Implementation



## Development of the RAAML Compliant STPA Toolset @ L3H SAS -Implementation





# Increased traceability and single location of safety analysis documentation



## Benefits doing STPA in a SysML Capable Modeling Tool



# Enhanced collaboration between Systems Safety and Systems Engineering resulting in improved efficiency and reduced costs



Development of the RAAML Compliant STPA Toolset @ L3H SAS - Update



Currently, L3H SAS is working to complete a RAAML compliant STPA Profile for use on future programs





## RAAML Compliance Facilitates: Shareability among Contractors, Customers and different MBSE toolsets



## **Benefits of using a RAAML Compliant STPA Tool Integration**



## **RAAML** Compliance Facilitates: Improved Error Detection





# Key Differences Between the STPA Profile 1.0 vs STPA Profile 2.0



### **STPA Profile 1.0**

#### STPA Profile 2.0

UCA and Loss Scenarios were grouped together as attributes of a single UCA ()

#### UCAs and Loss Scenarios are separate model elements

#	Name	UCA Type	UCA		Effect(s)	Causal Scenarios	Traced To	Traced From
1	BAUCA1.a.1	a. "is not provided when"	The Driver does not press the pedal when an obstacle is in oncoming path of the vehicle	E brake brake could res brake brake could res brake could res brake could res	icle will continue to move in nt direction. The speed of th and size/mobility of the ill determine the severity of ict. Worst case scenario sult in driver, passenger or (pedestrian or other vehicle leath/serious injury.	The driver is unaware there is an obstacle in the pathway of the vehicle.	Item Flow:flow for Press Brake Pedal[Driver -> Brake Control Module] H-1 H-2	E BASR.001 E BASR.002
		UCA - Profile 1.0		J		Loss Scena	rio - Profile 1.0	
UCA - Profile 2.0								
#	△ Name	Documentation	Base	Classifier	ControlAction	n		
1	UCA-1	The driver does not press the press the pedal when an obstacle is i oncoming path of the vehi	ne brake 🔚 NotP n cle.	rovided	Press Brake Ped	lal		
	Loss Scenario - Profile 2.0							

Allows for querying the model for specific UCAs and their associated loss scenarios

Loss Scenario - Profile 2.0									
#	Name	Documentation	Associated UCAs	ProcessModels	Factors	Mitigation	Situation Type		
1	📙 LS-1	Test Loss Scenario	UCA-1	Driver does not see obstacle	<ul> <li>Radar does not detect object</li> <li>No headlights to iluminate object</li> <li>Weather conditions obstruct driver's view of object</li> </ul>	📧 8 Test Requirement 😭 STPA1	LossScenario		



STPA Profile 1.0	STPA Profile 2.0
No use of Process Model elements in the model	Inclusion of distinct Process Model elements

## **Process Model - New for Profile 2.0**

#	Name	Documentation	Base Classifier	Associated LossScenario
1	Driver does not see obstacle	The driver is unaware of obstacle in pathway of the vehicle	InadequateFeedbackAndInputs	📙 LS-1

Similar Process Model and their effects can be queried to help identify trends that contribute to inadequate processes



### STPA Profile 1.0

#### **STPA Profile 2.0**

Operational Situations were included within the UCA description attribute

#### Operation Situations are a standalone element.

#	Name	UCA Type	UCA	Effect(s)	Causal Scenarios	Traced To	Traced From
1	BAUCA1.a.1	a. "is not provided when"	The Driver does not press the brake pedal when an obstacle is in oncoming path of the vehicle.	The vehicle will continue to move in its current direction. The speed of th evehicle and size/mobility of the object will determine the severity of the impact. Worst case scenario could result in driver, passenger or obstacle (pedestrian or other vehicle	The driver is unaware there is an obstade in the pathway of the vehide.	Item Flow:flow for Press Brake Pedal[Driver -> Brake Control Module] H-1 H-2	E BASR.001 BASR.002
Operational Situation Profile 1.0				Specific C multiple U can be tar	Operational Sce CAs and Loss S geted at specifi	narios can be a Scenarios, thus c phases of sys	ssociated with safety analysis tem operation.

1	<b>Operational Situation Profile 2.0</b>			
#	Name	Documentation	Base Classifier	Situation Type
1	Driving at speed under optimal weather conditions		AbstractOperationalSituation	AbstractOperationalSitu
2	Stopping for stop light/stop sign		AbstractOperationalSituation	AbstractOperationalSitu
3	📙 Parking on flat ground		AbstractOperationalSituation	AbstractOperationalSitu
4	📙 Parking on incline		AbstractOperationalSituation	AbstractOperationalSitu
5	📙 Lane Change		AbstractOperationalSituation	AbstractOperationalSitu



Factors that lead to a loss were included within the Loss Scenario statement       Factors that lead to a Loss Scenario are separate model elements         #       Name       UCA Type       UCA       Effect(s)       Causal Scenarios       Traced To       Traced Fre         #       Name       UCA Type       UCA       Effect(s)       Causal Scenarios       Traced To       Traced Fre         #       BAUCA1.a.1       a. "is not provided when"       The Driver does not press the brain pedal when an obstade is in oncoming path of the vehicle.       The vehicle will continue to move in its current direction. The speed of the object will determine the severity of the impact. Worst case scenario could result in driver, passenger or obstade (pedestrian or other vehicle driver) deat/serious intruv.       The driver is unaware there is an oncoming path of the vehicle.			STPA Profile	1.0		STPA	Profile 2.0	
Image: Name       UCA Type       UCA       Effect(s)       Causal Scenarios       Traced To       Traced Free         1       BAUCA1.a.1       a. "is not provided when"       The Driver does not press the brake pedal when an obstacle is in oncoming path of the vehicle.       The vehicle will continue to move in its current direction. The speed of the impact. Worst case scenario could result in driver, passenger or obstacle (pedestrian or other vehicle).       The driver is unaware there is an obstacle in the pathway of the vehicle.       Item Flow::flow for Press Brake control Module]       BASR.001		Factors that lead Scenario stateme	to a loss were incl ent	uded within the Lo	ss Factors th elements	at lead to a Loss S	Scenario are separa	ate model
BAUCA1.a.1       a. "is not provided when"       The Driver does not press the brake pedal when an obstade is in oncoming path of the vehicle.       The vehice will continue to move in its current direction. The speed of the object will determine the severity of the impact. Worst case scenario could result in driver, passenger or obstade (pedestrian or other vehicle driver) death/serious injury.       The vehice will continue to move in its current direction. The speed of the vehice and size/mobility of the object will determine the severity of the impact. Worst case scenario could result in driver, passenger or obstade (pedestrian or other vehicle driver) death/serious injury.       The vehice will continue to move in its current direction. The speed of the vehice and size/mobility of the object will determine the severity of the impact. Worst case scenario could result in driver, passenger or obstade (pedestrian or other vehicle)       The driver is unaware there is an obstade in the pathway of the vehice.       The driver is unaware there is an obstade in the pathway of the vehice.       H-1       H-2       H-2	•	Name	UCA Type	UCA	Effect(s)	Causal Scenarios	Traced To	Traced From
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		Factors Profile 2.0		
#	Name	Documentation	Situation Type	Associated LossScenario
1	📃 No headlights to iluminate object	Headlights will help the driver see objects in low light settings.	E Factor	LS-1
2	Weather conditions obstruct driver's view of object	Accumulation of precipitation on the windshield of the vehicle may cause the driver to not be able to see objects in the pathway of the vehicle	Factor	📙 LS-1
3	📕 Radar does not detect object	If the vehicle is equipped with a radar, failure or delay of the radar to detect an object may result in the driver not receiving a warning of an object in the pathway of the vehicle	Factor	E LS-1



### Summary of key points

- Organization adoption of STPA is slow, but Training and Tooling help sell STPA to the C-Suite
- STPA is MBSE
- Standardizing the use of STPA within a SysML environment will help further STPA adoption across industries

### Future plans for L3H SAS's RAAML compliant STPA tool

- L3H SAS will continue to develop its RAAML compliant STPA tool set to ensure complete compliance and usability
- Continue to find practitioners outside of the traditional System Safety role to further its use outside of safety critical systems (cyber security, mission success and organization process improvement)



Mark Relova, (Scientist, Systems Engineering – L3H SAS) and Lucas Gusman (Specialist, Systems Engineering) – L3H SAS who did the heavy lifting to transition STPA Profile 1.0 to STPA Profile 2.0!

OMG for the release of the RAAML Specification - https://www.omg.org/spec/RAAML



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